

Improving Newton Existence Test SWIM 2013

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Outline

- 1 Brouwer Fixed-Point Theorem
- 2 Newton Test for Existence and Uniqueness
- 3 Interval Newton Test
- 4 Improvements
- 5 Uniqueness Operator
- 6 Results and Conclusion



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Brouwer Fixed-Point Theorem

Brouwer Fixed-Point Theorem

Theorem (Euclidean space)

Every continuous function from a closed ball of an Euclidean space to itself has a fixed point.

Explanations - Anecdote

- 1D piece of string
- 2D sheet of paper
- 3D cup of coffee





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- 2 Newton Test for Existence and Uniqueness**
 - Definition
 - Explanations
 - Problem 1 - Jacobian invertibility
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Newton Test for Existence and Uniqueness

Definition

Consider a smooth function $\mathbf{f} : \mathbb{R}^n \rightarrow \mathbb{R}^n$ and $[\mathbf{x}] \in \mathbb{R}^n$.
Denote by \mathbf{J}_f is Jacobian Matrix.

Definition (Newton test, Moore [Moore, 1979])

The Newton operator is defined by

$$\mathcal{N}(\mathbf{f}, [\mathbf{J}_f], [\mathbf{x}]) = \hat{\mathbf{x}} - [\mathbf{J}_f]^{-1}([\mathbf{x}]) \cdot \mathbf{f}(\hat{\mathbf{x}}) \quad (1)$$

If $\mathcal{N}([\mathbf{x}]) \subset [\mathbf{x}]$ then $[\mathbf{x}]$ contains a unique zero \mathbf{x}^* of \mathbf{f} . It is also in $\mathcal{N}([\mathbf{x}])$.



Moore, R. E. (1979).
Methods and Applications of Interval Analysis.
SIAM, Philadelphia, PA.

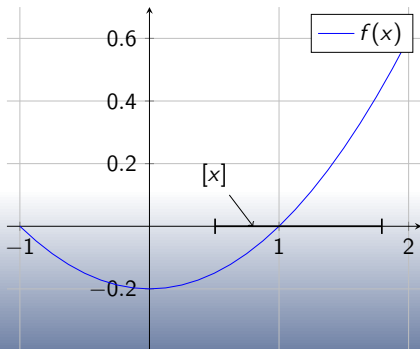


Newton Test for Existence and Uniqueness

Explanations

Take a function $f : \begin{cases} \mathbb{R} & \rightarrow & \mathbb{R} \\ x & \mapsto & 0.2(x^2 - 1) \end{cases}$. We want to prove existence and uniqueness of $f(x) = 0, \forall x \in [0.5, 1.8]$.

- Choose an initial domain for $[x]$





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- Choose an initial domain for $[x]$
- Evaluate slopes over $[x]$

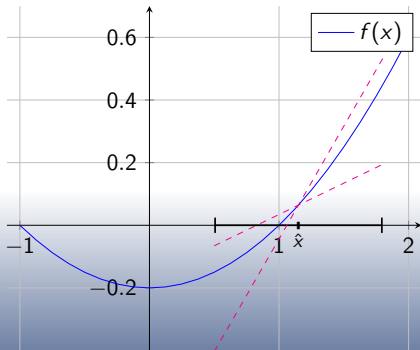


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- Choose an initial domain for $[x]$
- Evaluate slopes over $[x]$
- Center slopes on \hat{x}



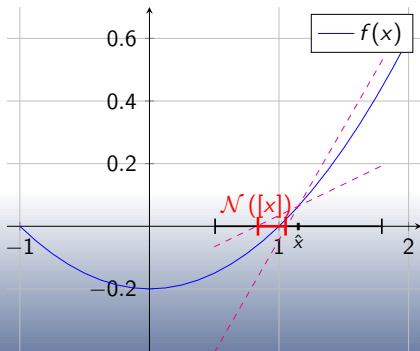


Newton Test for Existence and Uniqueness

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- Choose an initial domain for $[x]$
- Evaluate slopes over $[x]$
- Center slopes on \hat{x}
- Intersection gives us $\mathcal{N}([x])$





Newton Test for Existence and Uniqueness

Problem 1 – Jacobian invertibility



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Interval Newton Test

Definitions

An uncertain function \mathbf{f} could be described in several ways:

- ① As a tube: $\mathbf{f} \in [\mathbf{f}]$ with $[\mathbf{f}] \triangleq [\mathbf{f}^-, \mathbf{f}^+]$
- ② As a parametrized function: $\mathbf{f} \in [\mathbf{f}]$ with $[\mathbf{f}] = \{\varphi(\mathbf{p}, \mathbf{x}), \mathbf{p} \in [\mathbf{p}]\}$

If $J_{\mathbf{f}} \in [J_{\mathbf{f}}]$, we define:

Definition (Interval Newton Test)

$$\mathcal{N}([\mathbf{f}], [J_{\mathbf{f}}], [\mathbf{x}]) = \hat{\mathbf{x}} - [J_{\mathbf{f}}]^{-1}([\mathbf{x}]) \cdot [\mathbf{f}](\hat{\mathbf{x}}) \quad (2)$$

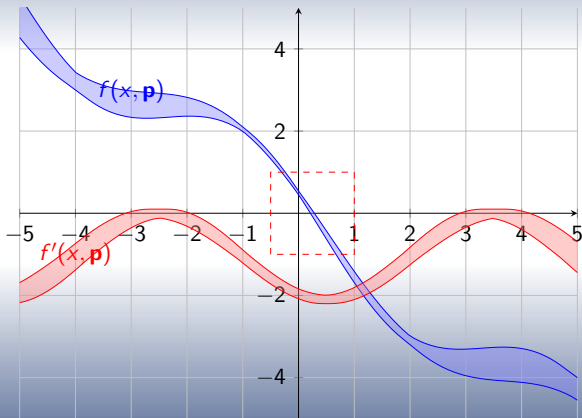
$$\mathcal{N}([\mathbf{x}]) = \hat{\mathbf{x}} - \Sigma([J_{\mathbf{f}}]([\mathbf{x}]), [\mathbf{f}](\hat{\mathbf{x}})) \quad (3)$$



Interval Newton Test

Explanations

Take a function $f(x, [\mathbf{p}]) = \cos(p_1 \cdot x + p_2) - p_3 \cdot x$ with $[\mathbf{p}] = [1, 1.1]^3$.

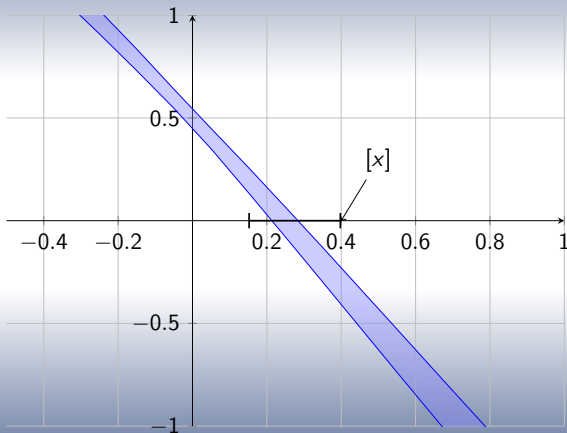




Interval Newton Test

Example

We want to prove: $\forall \mathbf{p} \in [\mathbf{p}], \exists ! x, f(x, \mathbf{p}) = 0$

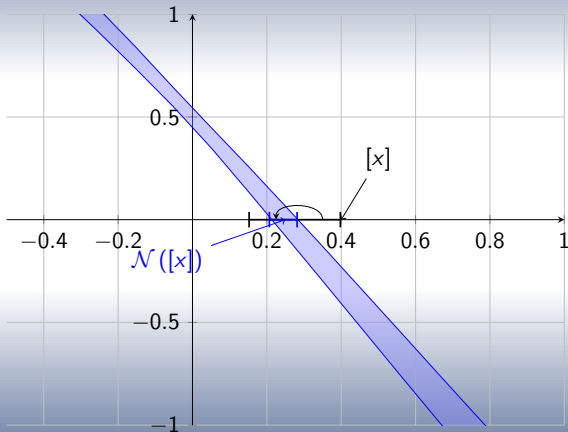




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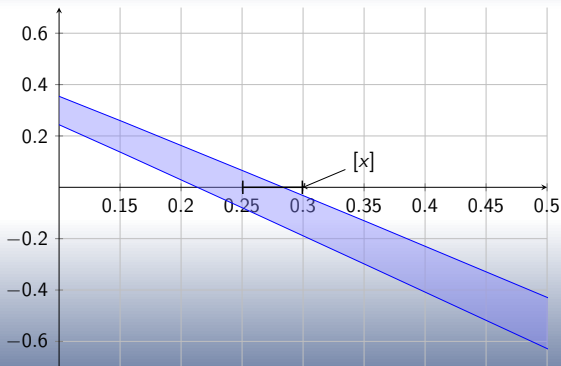


Interval Newton Test

Problem 2 - Bad initial box

When $[x]$ is overlapping $X_0 = \{x \mid 0 \in [f](x)\}$ and $X_0 \not\subseteq [x]$, we must start an iteration process.

We want to prove: $\forall \mathbf{p} \in [\mathbf{p}], \exists! x \in [0.25, 0.3], f(x, \mathbf{p}) = 0$



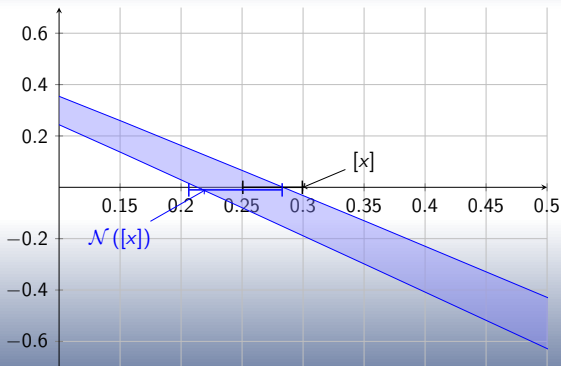


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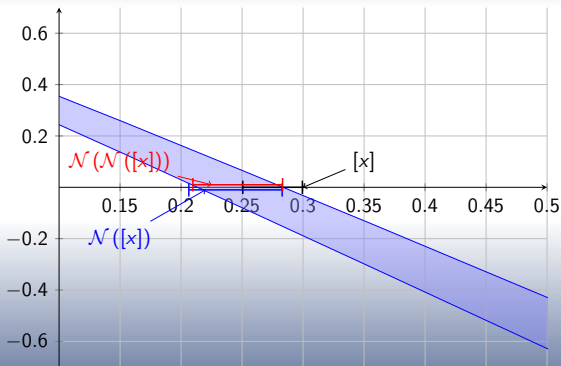


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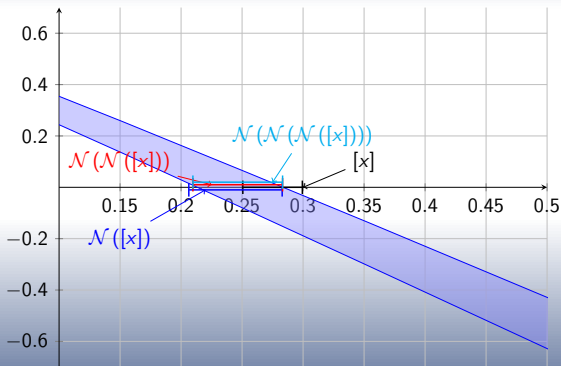


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\mathcal{E} -inflation

Original definition of \mathcal{E} -inflation by Rump [Rump, 1980].

Definition

For a real interval $[x]$

$$[x] \circ \mathcal{E} = \begin{cases} [x] + w([x]) \cdot [-\mathcal{E}, +\mathcal{E}] & \text{for } w([x]) \neq 0 \\ [x] + [-\eta, +\eta] & \text{otherwise} \end{cases} \quad (4)$$

where η represents the smallest representable machine number and \mathcal{E} the inflation coefficient.



Rump, S. M. (1980).

Kleine fehlerschranken bei matrixproblemen.
Dissertation, Universität Karlsruhe.

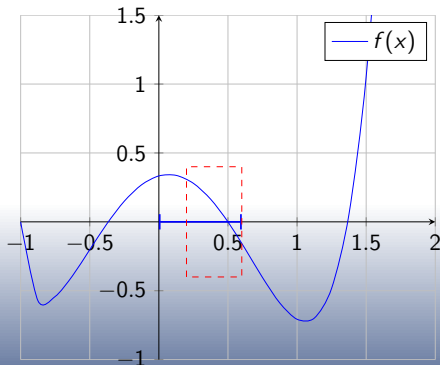


Improvements

N-inflation

Idea: Replace initial box $[x]$ by a small sized interval in $[x]$.
Iterate with \mathcal{E} -inflated input, $\mathcal{E} = \eta$.

- $$f(x) = \frac{(4x^3 - 6x + 1)(\sqrt{x+1})}{3-x}$$



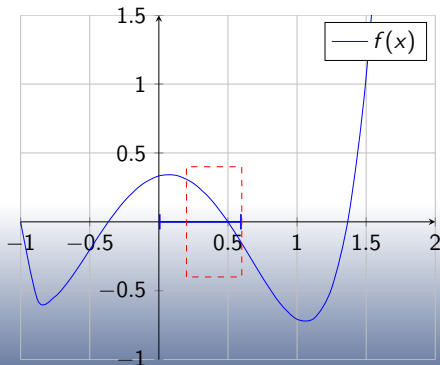


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- $\mathcal{N}([0; 0.6]) = [-\infty, +\infty]$



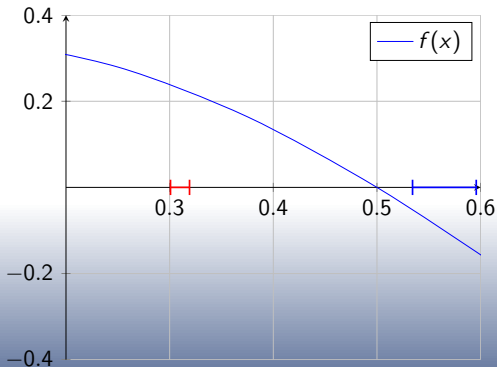


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- $\mathcal{N}([0; 0.6]) = [-\infty, +\infty]$
- $\mathcal{N}([0.3; 0.32]) = [0.5335; 0.5966]$



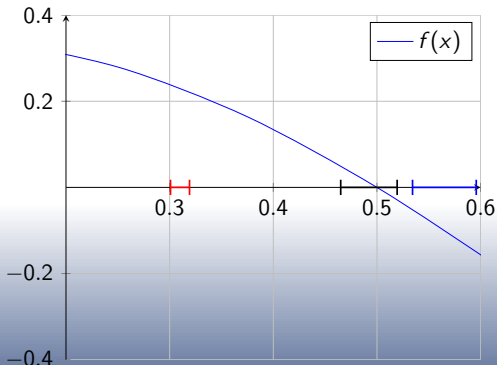


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- $\mathcal{N}^2([0.3; 0.32]) = [0.4642; 0.5203]$



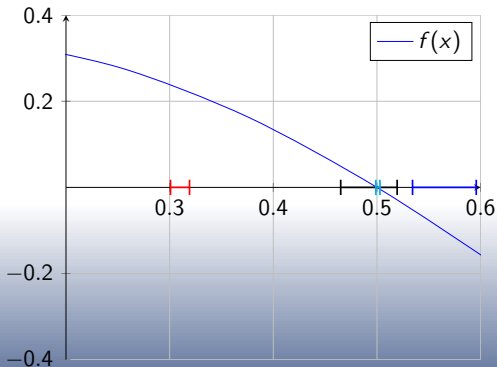


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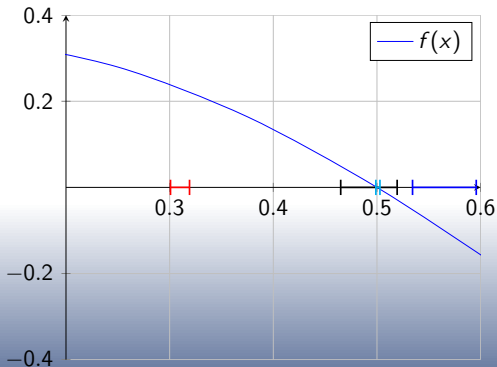


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- $\mathcal{N}^3([0.3; 0.32]) = [0.4981; 0.5037]$
- $\mathcal{N}^3([0.3; 0.32]) \subset \mathcal{N}^2([0.3; 0.32])$



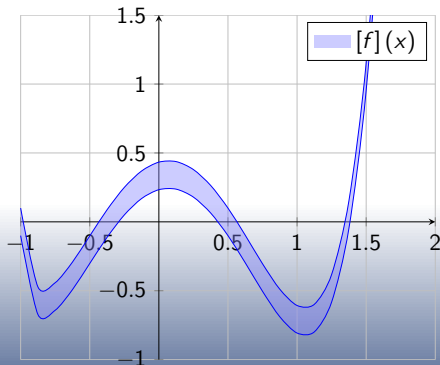


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- Similar when $f \in [f], \hat{f} \in [\hat{f}]$



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Proposition
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Uniqueness Operator

Definition

Definition (Uniqueness Operator)

$\mathcal{N} : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a **uniqueness operator** if it verifies:

$$\mathcal{N}([x]) \subset [x] \Rightarrow \exists! \mathbf{x}^* \in [x], \mathcal{N}(\{\mathbf{x}^*\}) = \{\mathbf{x}^*\} \quad (5)$$

Proposition ([Delanoue, 2006])

If an operator \mathcal{N} is a uniqueness operator. So does \mathcal{N}^k , with $\mathcal{N}^k = \mathcal{N} \circ \mathcal{N} \circ \dots \circ \mathcal{N}$.



Delanoue, N. (2006).

Algorithmes numériques pour l'analyse topologique.

PhD dissertation, Université d'Angers, Angers, France.



Uniqueness Operator

Proposition

Definition (N-Kleene)

$$I \cap \mathcal{N} \cap \mathcal{N}^2 \cap \dots \cap \mathcal{N}^\infty = \mathcal{N}^* \quad (6)$$

- If \mathcal{N} is a uniqueness operator for a box $[x]$, so does \mathcal{N}^* .
- \mathcal{N}^* is more efficient than \mathcal{N} .



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Results and Conclusion

Results - Loop Detection

Problem Statement (Loop detection [Aubry et al., 2013])

We search:

$$\mathbf{f}(\mathbf{t}) = 0, \mathbf{t} = (t_1, t_2) \text{ a } t\text{-pair} \quad (7)$$

$$\text{With } \mathbf{f}(\mathbf{t}) = \int_{t_1}^{t_2} \mathbf{v}(\tau) d\tau$$

$$\mathbf{v} \in [\mathbf{v}] \Rightarrow \mathbf{f} \in [\mathbf{f}]$$

$$\mathbf{J}_{\mathbf{f}} = (-\mathbf{v}(t_1) \quad \mathbf{v}(t_2)) \in (-[\mathbf{v}](t_1) \quad [\mathbf{v}](t_2))$$

2 equations, 2 unknown, parameter in infinite dimension.



Aubry, C., Desmare, R., and Jaulin, L. (2013).

Loop detection of mobile robots using interval analysis.

Automatica, 49(2):463–470.

Demo Loop Detection and N-inflation.



Conclusion

Results

- Decrease probability of Jacobian non-invertibility.
- Strategy: local research of a uniqueness box.
- Better automation of uniqueness tests.

To go further

- Perform benchmarking.
- Test with different solver in Newton operator definition.

Thanks for your attention.
Questions?