

Constructive Interval Disjunction (CID)

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Outline

- 1 Motivations
- 2 A hybrid 3B / CID algorithm
- 3 CID-based splitting strategy
- 4 Experiments
- 5 Conclusion

Constructive Interval Disjunction

- **Constructive disjunction** (by Van Hentenryck et al. at ECRC) was introduced to handle disjunctions of constraints:
application to scheduling, bin packing...
- In finite-domain CSPs, constructive disjunction can be applied to the variable domains ($x = v_1 \vee \dots \vee x = v_n$):
success on Sudoku
- Question: can “**constructive domain disjunction**” be applied to **numerical CSPs** ?

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- Question: can **“constructive domain disjunction”** be applied to **numerical CSPs** ?

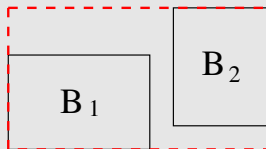
Contributions

- Study of **shaving** (3B) and **constructive disjunction** in numerical CSPs
- Definition of a new partial consistency called **constructive interval disjunction (CID)**
- Design of a contraction operator computing CID
- Design of a hybrid operator 3B/CID
- Design of a new splitting strategy based on CID

CID-consistency

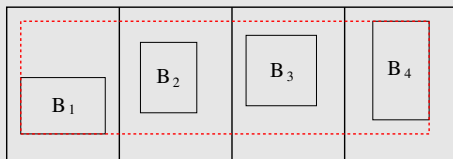
The **Hull** operator (union)

$\text{Hull}(B_1, B_2)$ is the minimal box including boxes B_1 and B_2 .



CID(s)-consistency ... informally

- ① Cut the interval of variable x in s slices ($s = 4$ here).
- ② Apply a sub-contracting operator ($2B$ or $B_{\circ x}$) on the sub-boxes.
- ③ Take the hull of the contracted sub-boxes.



x

A first CID operator: $CID(s, w)$

Algorithm CID (s : number of slices, w : precision, in-out $P = (X, C, B)$: an NCSP, F : subfiltering operator and its parameters)

```

repeat
  LoopCID( $X, s, P, F$ )
until StopCriterion( $w, P$ )

```

end.

Procedure LoopCID($X, s, in-out P, F$)

```

for every variable  $xi \in X$  do
  VarCID( $xi, s, P, F$ )
end

```

end.

Procedure VarCID($xi, s, (X, C, in-out B), F$)

```

 $B' \leftarrow$  empty box
for  $j \leftarrow 1$  to  $s$  do
  sliceBox  $\leftarrow$  SubBox( $j, s, xi, B$ ) /* the  $j^{th}$  sub-box of  $B$  on  $xi$  */
  sliceBox'  $\leftarrow$   $F(X, C, sliceBox)$  /* perform a partial consistency */
   $B' \leftarrow$  Hull( $B', sliceBox'$ ) /* Union with previous subboxes */
end
 $B \leftarrow B'$ 

```

end.

A CID-based solving scheme

An efficient CID-based solving scheme

Loop until small boxes (solutions) are obtained:

- CID filtering : $CID(s, w-hc4, n')$
- Interval Newton
- Bisection

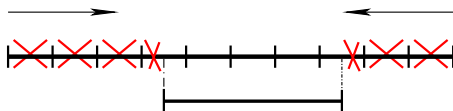
Experimental feedback

- The right number s of slices $\in [2, 8]$ (default value = 4).
- Reaching a fixed-point (based on w) is not fruitful \Rightarrow only one iteration on all the variables ($Loop_{CID}$) between two bisections.
- Tuning the number n' of variables that are varcided between two bisections may be fruitful.

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3B-consistency



CID and 3B (by Olivier Lhomme) have common points and differences.

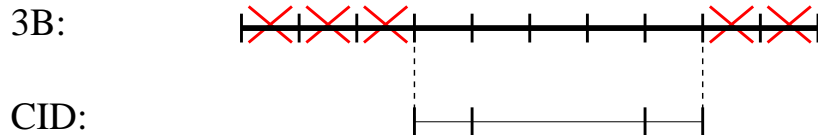
- When the subfiltering process provides an empty box, 3B and CID yield the same result.
- Otherwise, CID is stronger: CID performs a union between sub-boxes whereas 3B does simply nothing.
- - Constructive disjunction applied to a single variable (i.e., VarCID) reduces the box in **all** dimensions.
 - Shaving a variable reduces the box in **one** dimension.

3BCID: a hybrid 3B/CID filtering algorithm

Principle:

- 1 Three parameters: a maximum number of slices s_{3B} (for the 3B part), a number of slices s_{CID} (for the CID part), a width w_{hc4} ($2B/Box$).
- 2 For every interval, `VarShavingCID` first performs a `VarShaving` and then a `VarCID` with $s_{CID} + 2$ slices.

Example: `VarShavingCID` ($s_{3B}=10$, $s_{CID}=1$, w_{hc4})



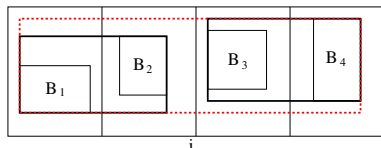
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A new splitting strategy

- A `VarCID` operation **learns for free** a relevant information
- called **ratioBis**.

$$\text{ratioBis} = \frac{\text{Size}(B'_i) + \text{Size}(B''_i)}{2 \times \text{Size}(\text{NewBox})}$$

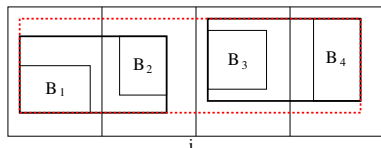


- New CID-based splitting strategy: after a call to `LoopCID`, one selects the variable with the lowest `ratioBis`.
- `ratioBis` computes the size lost by the `Hull` operation, as compared to a bisection.
- `ratioBis` computes the size lost for avoiding a combinatorial explosion.
- Drawback: The evaluation of the lost size is exact only for the last variable \Rightarrow `ratioBis` is not “up-to-date” for the first `varcided` variables.

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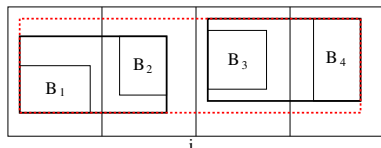


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Benchmarks and interval-based solver

Twenty benchmarks of medium difficulty:

- Five sparse (geometric) systems: Hourglass, Tetra, Tangent, Ponts, Mechanism
- Fifteen benchmarks found in COCONUT and/or the COPRIN team Web pages

Implementation on a new interval-based solver

- Solver in C++ developed by Gilles Chabert
- Precision: $1e-08$ ($5e-06$ for Mechanism)
- Local filtering: 2B (2B+Box for Yamamura8)
- Tests performed on a Pentium IV 2.66 Ghz

[CID+Newton+bisection] vs [2B+Newton+bisection]

Nom	n	#s	whc4	2B/Box	CID	CID (n')	CID (w)	CID ($()$)	s
Broy.	32	2	15%	758 2e+07	0.12 46	0.28 44	0.19 65	0.45 50	4
Hourg.	29	8	5%	24 1e+05	0.44 109	0.44 109	0.52 80	0.52 80	4
Tetra	30	256	0.02%	401 1e+06	10.1 2116	11.6 1558	11.7 1690	14.5 1320	4
Tang.	28	128	15%	32 1e+05	3.7 692	3.7 692	4.9 447	5.1 450	4
React.	20	38	5%	156 1e+06	15.6 2588	16.4 2803	16.7 2381	17.7 2156	4
Trig.1	30	1	20%	371(3.4) 5025	0.12 1	0.15 3	0.14 2	0.14 3	8
Disc.	27	1	0.01%	5.2 1741	0.62 2	1.08 3	0.84 12	2.13 99	8
I5	10	30	2%	692 3e+06	126 23105	147 60800	150 20874	157 32309	6
Trans.	12	1	10%	179 1e+06	66 11008	79.4 31426	91.4 16333	91.4 16333	8
Ponts	30	128	5%	10.8 34994	2.7 388	2.9 338	2.9 380	3.1 304	4

[CID+Newton+bisection] vs [2B+Newton+bisection]

Nom	n	#s	whc4	2B/Box	CID	CID (n')	CID (w)	CID ()	s
Yamam8	8	7	1%	13 1032	7.5 104	9.5 60	9.5 60	9.5 60	4
Design	9	1	10%	395 3e+06	275 2e+05	278 2e+05	313 76633	313 76633	5
D1	12	16	5%	4.1 35670	1.7 464	1.7 464	1.7 464	1.7 464	4
Mechan.	98	448	0.5%	TO(111) 24538	43.1 3419	45.2 3300	46.6 2100	47.8 2420	4
Hayes	8	1	0.01%	155 3e+05	75.8 1e+05	77 1e+05	111 81750	147 58234	4
Kin1	6	16	10%	84 70368	76.8 6892	76.8 6892	83.5 4837	87.4 4100	4
Eco9	8	16	10%	26 2e+05	18 55657	19.4 46902	26.6 10064	26.6 10064	3
Belli.	9	8	10%	80 7e+05	94.4 1e+05	94.4 1e+05	106 45377	106 45377	4
Trig.2	9	1	20%	61.8	50.4	65.14	62.4	68.4	6
Trig.2	5	1	20%	3.0 13614	3.8 10221	4.6 4631	6.2 2293	6.6 1887	2
Capras.	4	18	30%	2.6	2.73	3.0	4.7	5.1	2

Observations

- Drastic reduction in the number of required bisections
⇒ good filtering power of CID
- Impressive gains in performance obtained by CID on the benchmarks on the top of the table.
- CID (n') allows a continuum between pure 2B/Box and CID.
- Due to a combinatorial consideration, CID should not be used for systems with a small number of variables.

CID VS 3B VS 3BCID

Nom	n	2B/Box	CID	3B	3BCID($s_{cid} = 1$)	3BCID($s_{cid} = 2$)
BroydenTri	32	758	0.23	0.22	0.18	0.19
Hourglass	29	24	0.45	0.73	0.43	0.50
Tetra	30	401	13.6	20.7	17.1	18.8
Tangent	28	32	4.13	8.67	3.18	4.13
Reactors	20	156	18.2	24.2	15.5	16.9
Trigexpl	30	3.4	0.10	0.26	0.12	0.11
Discrete25	27	5.2	1.37	2.19	1.26	1.13
I5	10	692	139	144	115	123
Transistor	12	179	71.5	77.9	49.3	46.9
Ponts	30	10.8	3.07	5.75	4.19	4.43
Yamamura8	8	13	9.0	9.1	10.3	10.7
Design	9	395	300	403	228	256
D1	12	4.1	1.78	2.99	1.64	1.76
Mechanism	98	111	79	185	176	173
Hayes	8	155	99	188	102	110
Kinematics1	6	84	76.1	136	76.6	81.4
Eco9	8	26	19.3	40.1	27.0	30.3
Bellido	9	80	95	143	93	102
Trigexp2-9	9	61.8	52.2	74.5	39.9	45.1
Caprasse	4	2.6	3.1	9.38	4.84	5.35

Observations

Main observations

- Protocol: 7-9 values of parameters have been tried for every algorithm; $w\text{-hc4} = 5\%$
- 3BCID and CID always outperform 3B.
- 3BCID is competitive with CID.

⇒ 3BCID with $s_{cid} = 1$ is a promising variant of 3B!

Comparison between splitting strategies

Filtering	CID	CID	CID
Bisection	Round-robin	Largest Int.	CID-based
BroydenTri	0.21	0.18	0.17
Hourglass	0.52	0.51	0.37
Tetra	12.1	28.2	16.4
Tangent	3.7	21.7	5.2
Reactors	17.0	13.2	12.7
Trigexpl	0.15	0.19	0.14
Discrete25	0.84	1.49	1.06
I5	151	421	179
Transistor	93	36	41
Ponts	2.92	5.51	2.31
Yamamura8	9.5	6.9	5.1
Design	318	334	178
D1	1.72	2.96	2.50
Hayes	115	564	318
Kinematics1	83	70	63
Eco9	26.7	31.4	26.1
Bellido	107	102	99
Trigexp2-9	62	55	53
Caprasse	5.16	5.43	5.04

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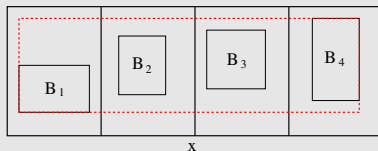
(Past !) Conclusion

- Splitting is a **combinatorial** way to refute parts of the search space (a tree search).
CID-consistency and 3B-consistency operators are **polynomial** ways to refute parts of the search space.
- CID (n') has the potential to subsume other filtering operators.
- 3BCID with $s_{cid} = 1$ is a promising variant of 3B.

Present: CID in 2008

Missing **Incrementality**

- All the slides need not be handled by `VarCID`!



Present consequences

- The right number of slices has increased (e.g., $s = 10$).
- `CID08R` manages a ratio (fixed to 90%) : for each variable (in `VarCID`), the loop on the slices is stopped once the current (hull) box has a perimeter greater than 90% of the initial box

Present: CID in 2008

Other remarks/modifications

- 3BCID with $s_{cid} = 1$ and incrementality is a very good contraction algorithm
- Separation of the job of shaving (from all the variables to one) and constructive disjunction (from one to all)
⇒ The CID-based splitting heuristic is now more robust...

Future: CID in 2009?

Adaptive variant based on:

- Incrementality
- Separation of shaving and constructive disjunction principles
- 2-CID varciding 2 variables simultaneously (equivalent to 4B) might work (with incrementality!).
- n' can be tuned in an adaptive way.
- ...