

# Improving the Ray Tracing of Implicit Surfaces using Interval Arithmetic

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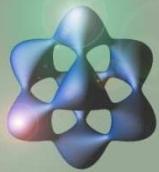


*Small Workshop on Interval Methods  
Montpellier, June 19-20, 2008*



## Section 1

# Introduction



## Introduction

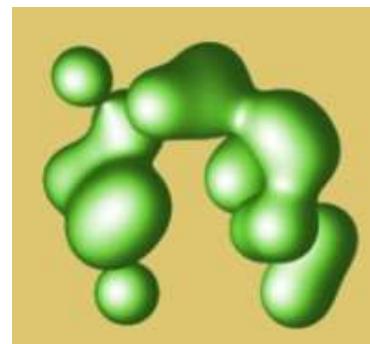
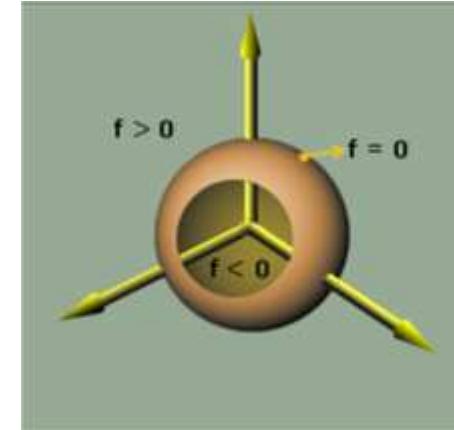
# Implicit Surfaces (IS)

$$f: \Omega \in \mathbf{R}^3 \longrightarrow \mathbf{R}$$

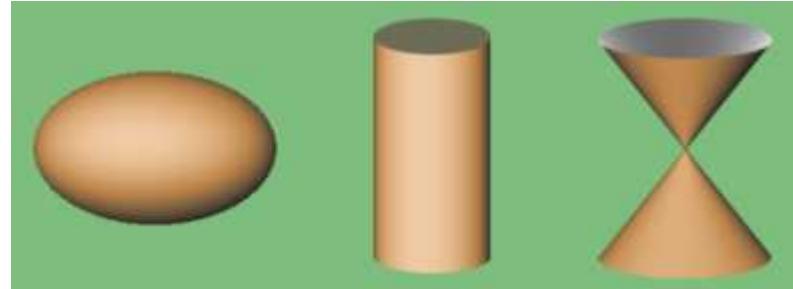
$f(x, y, z) = 0$  : Surface

$f(x, y, z) < 0$  : Points Inside (volume)

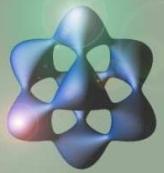
$f(x, y, z) > 0$  : Points Outside



Blobs



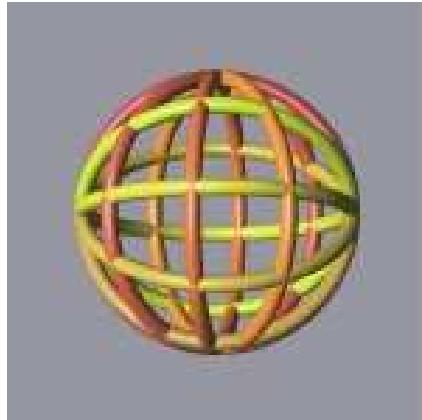
Quadratics

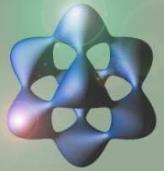


## Introduction

# Application of IS

Modeling using Constructive Solid Geometry operations





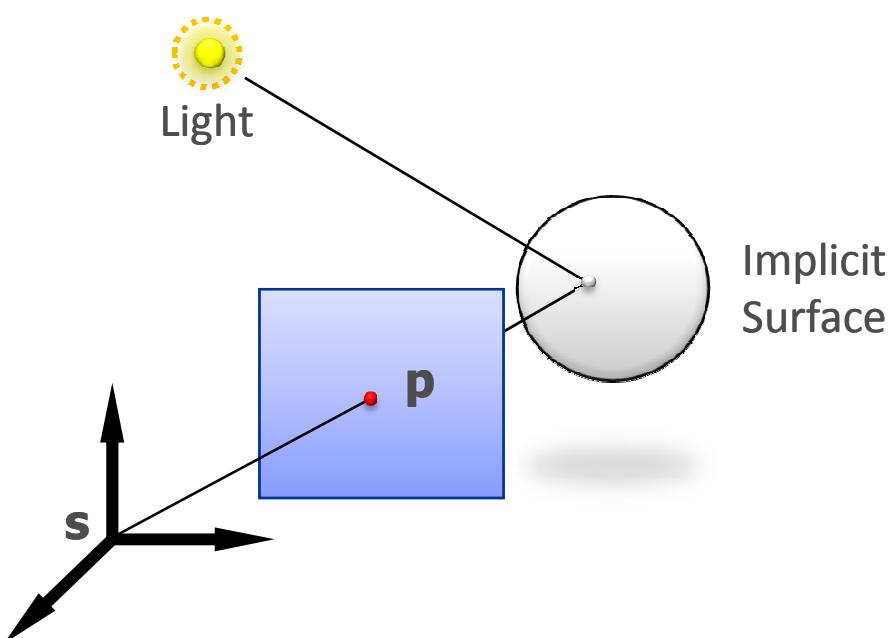
## Introduction

# Ray Tracing IS

### Intersection test

$$x = \underbrace{s_x + t(x_p - s_x)}_{\text{ray equation}}, \quad y = \underbrace{s_y + t(y_p - s_y)}_{\text{ray equation}}, \quad z = \underbrace{s_z + t(z_p - s_z)}_{\text{ray equation}}$$

$$F(t) = F(s_x + t(x_p - s_x), s_y + t(y_p - s_y), s_z + t(z_p - s_z))$$



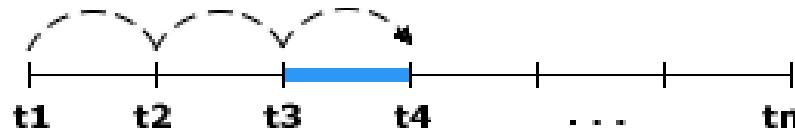
Improving the Guaranteed Ray Tracing of Implicit surfaces  
using Interval Arithmetic



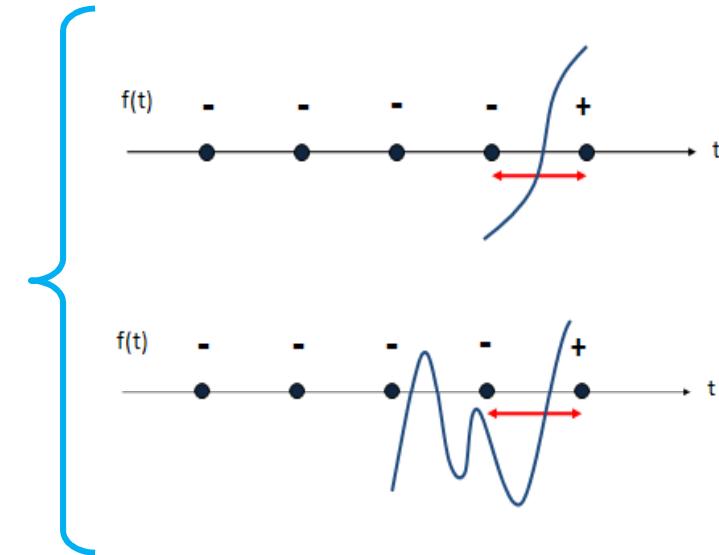
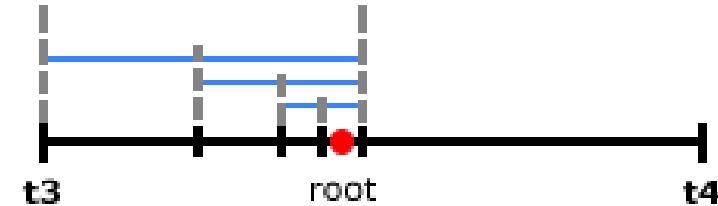


### Using point sampling

Root isolation



Root refinement



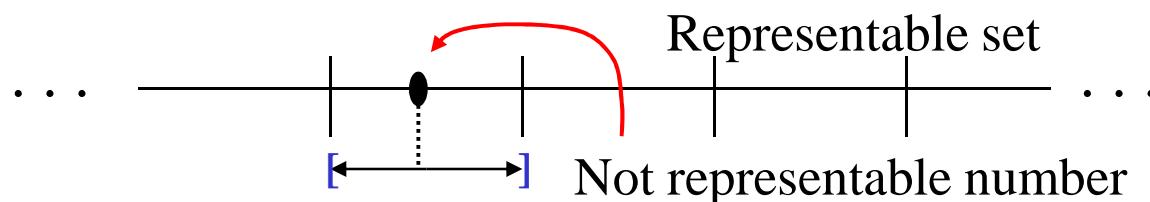
### Solution approaches

Lipschitz constants, [Interval Arithmetic](#), Affine arithmetic

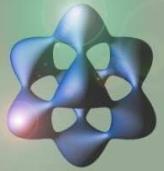


### Interval Arithmetic

- Computers can not represent all the set of real numbers: rounding problems.
- Interval Arithmetic:

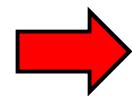


- Successfully applied in different areas: structures, control, supervision, medicine.



### Interval Ray Tracing IS (ii)

$$F(T) = F(s_x + T(x_p - s_x), s_y + T(y_p - s_y), s_z + T(z_p - s_z))$$



$0 \notin F(T)$ : The interval  $T$  does not contain roots.

#### **Mitchell**

- Solve root isolation using IA (Bisection, Interval Newton)

#### **Capriani et al.**

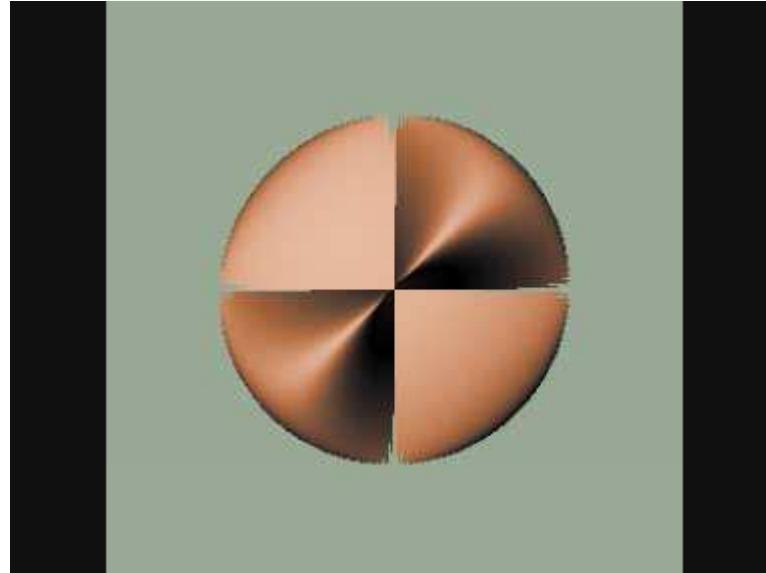
- Alefeld-Hansen operator combined as a complement of Interval Newton Method

#### **San Juan et al. (MRFro)**

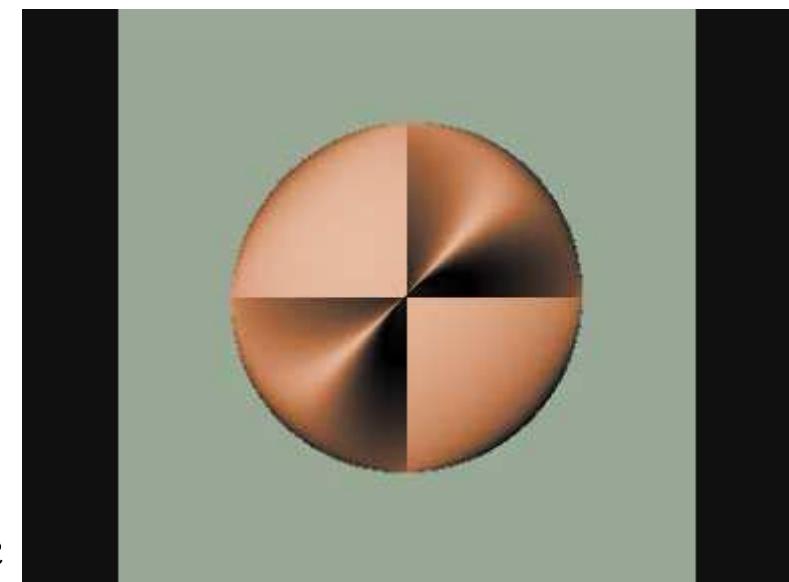
- Improved bisection using conditionals



### Point sampling vs. IA



Point sampling

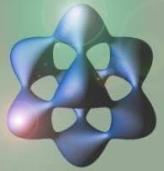


Interval Arithmetic



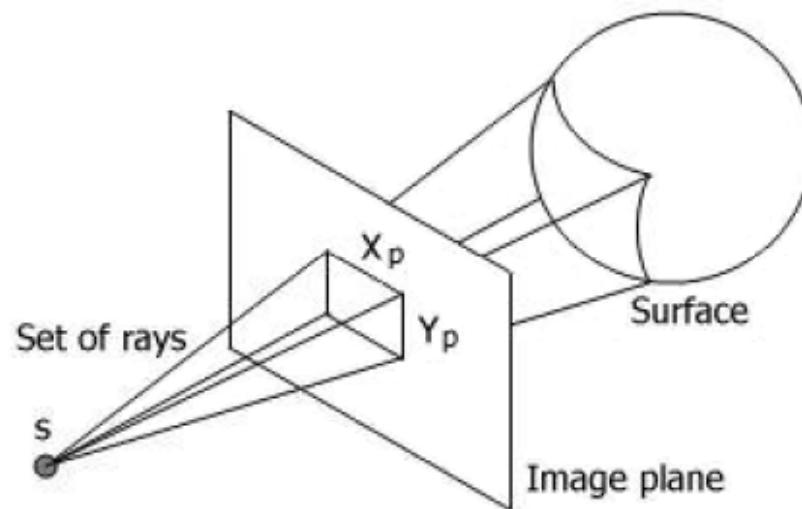
## Section 2

# Efficiency improvement

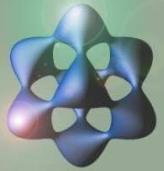


### Evaluating a Set of Rays

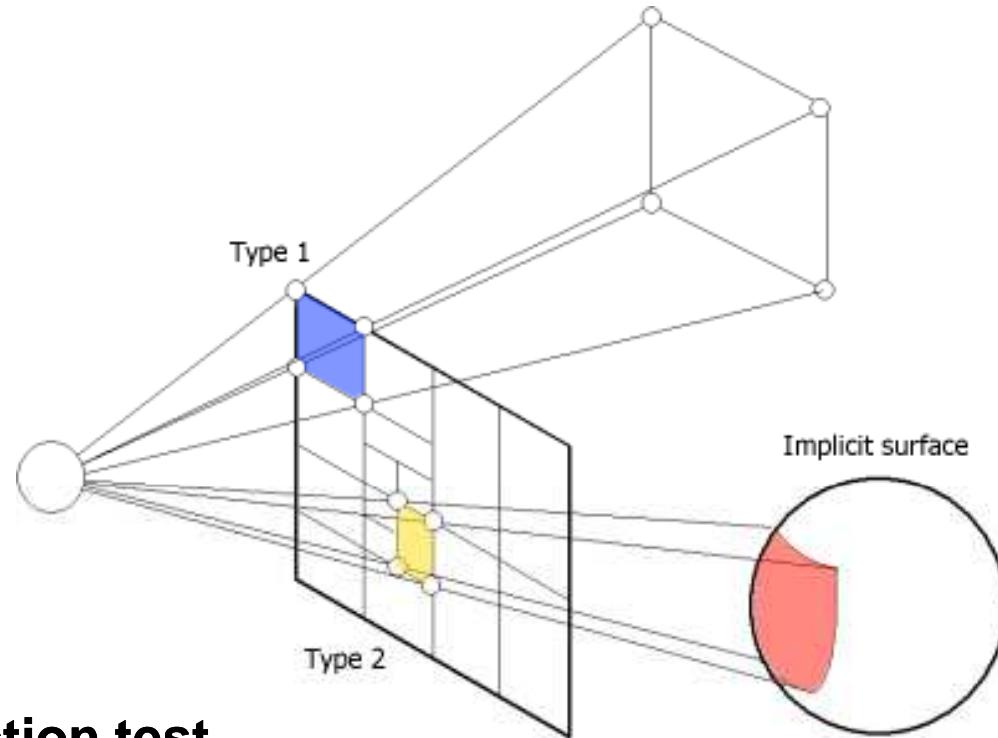
$$F(T, X_p, Y_p) = F(s_x + T(X_p - s_x), s_y + T(Y_p - s_y), s_z + T(z_p - s_z))$$



Evaluation of a set of rays instead of a unique ray



### Evaluating areas instead of points



#### Rejection test

- Identify areas without rays intersecting the surface

#### Inclusion test

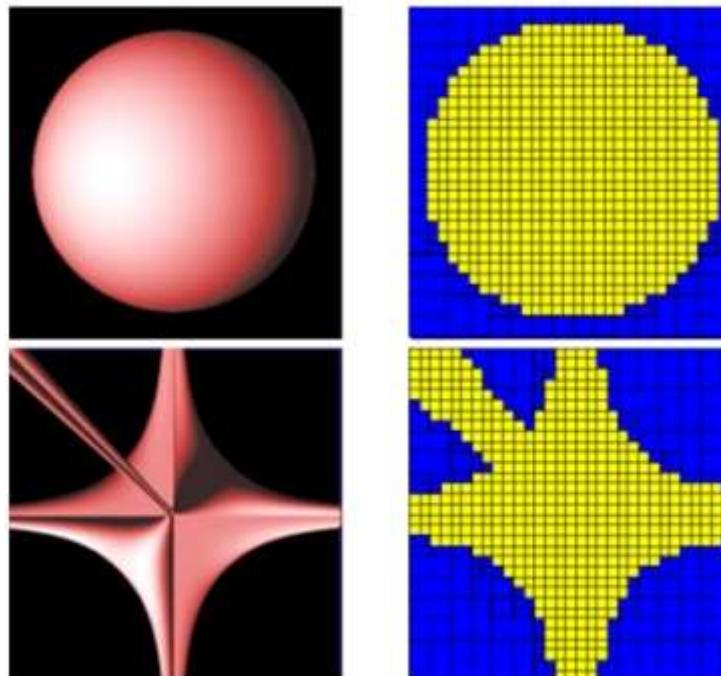
- Identify areas in which all the rays intersect the surface



### Rejection Test (i)

#### Semantic:

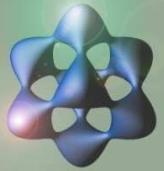
- “For all values of X, and for all values of Y, for all the values of T,  $0 \notin fR(X, Y, T)$  ”





### Rejection Test (ii)

```
Function Reject(Intervals  $X_s, Y_s, Z_s$ )
     $T = \text{Interval}(0, t)$ 
    add  $T$  to ListT
    For every  $T$  in ListT
        If Width( $T$ ) <  $\epsilon_T$ 
            Exit For
        EndIf
        If  $0 \notin fR(X_s, Y_s, T)$ 
            Drop  $T$  from ListT
        Else
            Bisect  $T$  into  $T_1, T_2$ 
            Add  $T_1, T_2$  to ListT
        EndIf
    EndFor
    If empty(ListT)
        Box does not have Intersections
    Else
        Box can have Intersections
    EndIf
```

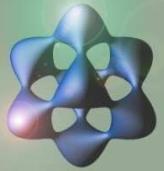


## Improving Efficiency

### Inclusion Test (i)

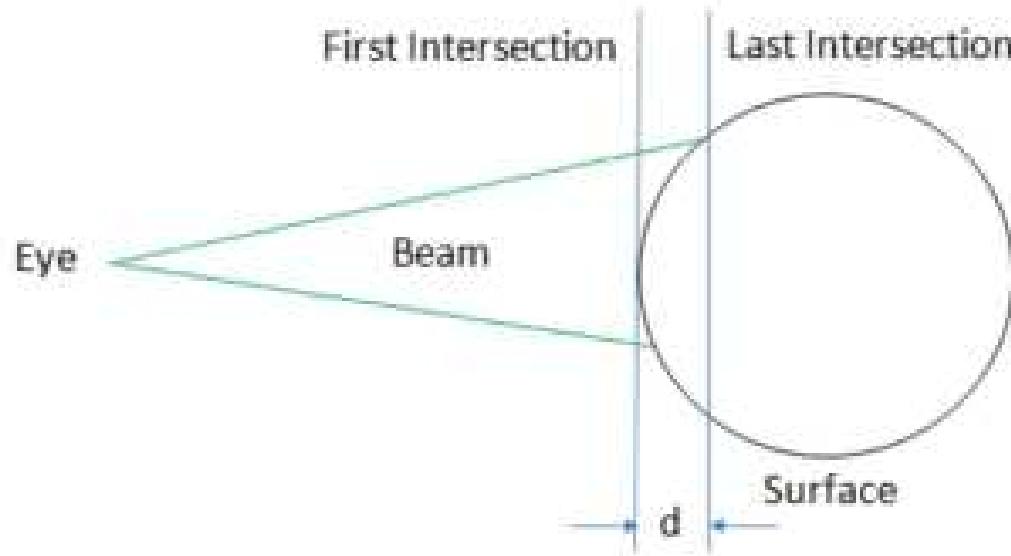
“For all values of X, and for all values of Y, there are values of T,  $0 \in fR(X, Y, T)$

```
Function Include(Intervals  $X_s, Y_s$ )
    Meet=[ $-\infty, \infty$ ]
    T=Interval(0, $\infty$ )
    add T to ListT
    For every T in ListT
        If Width(T) <  $\epsilon_T$ 
            Exit For
        EndIf
        If  $0 \in fR(X_p, Y_p, T)$ 
             $R_a = fR(X_p, Y_p, T.Inf)$ 
             $R_b = fR(X_p, Y_p, T.Sup)$ 
            Meet = Meet  $\wedge R_a \wedge R_b$ 
        If  $0 \in Meet$ 
            The Beam Intersects completely the surface
        Else
            Bisect T into  $T_1, T_2$ 
            Add  $T_1, T_2$  to ListT
        EndIf
    EndIf
EndFor
```



### Inclusion Test (ii)

- Also, the distance between the first and last intersection is used to measure the change of the surface inside the area.

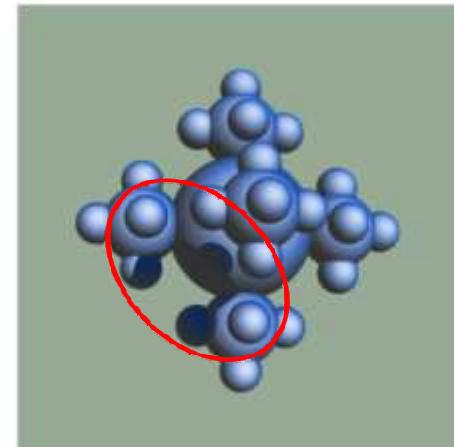
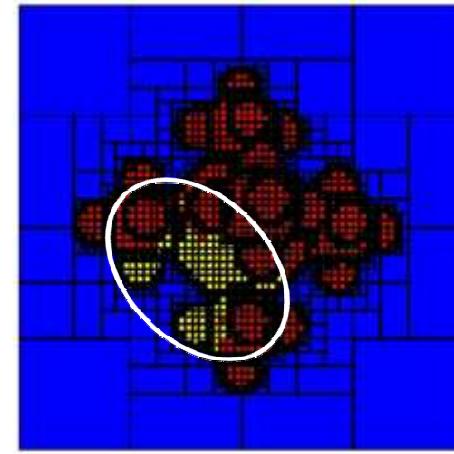
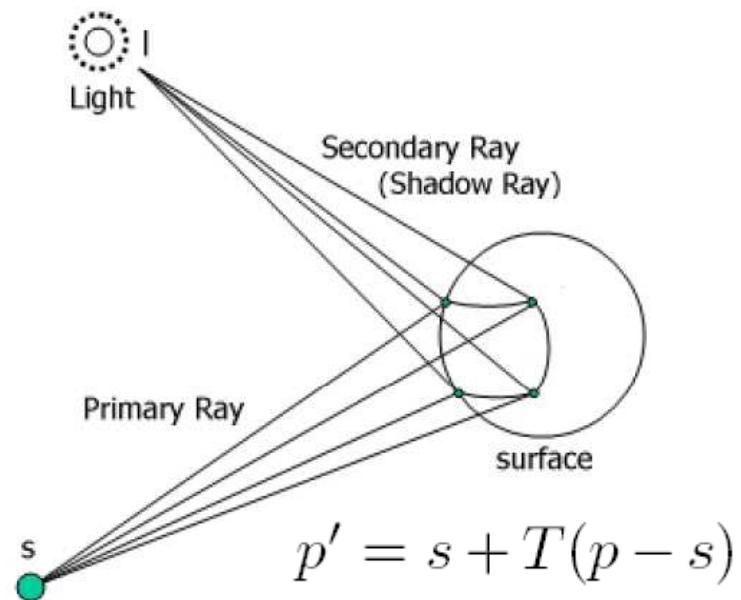




## Improving Efficiency

### Shadow Regions

- Used only for Inside Regions



Shadow Ray :  $r'(T') = l + T'(p' - l)$

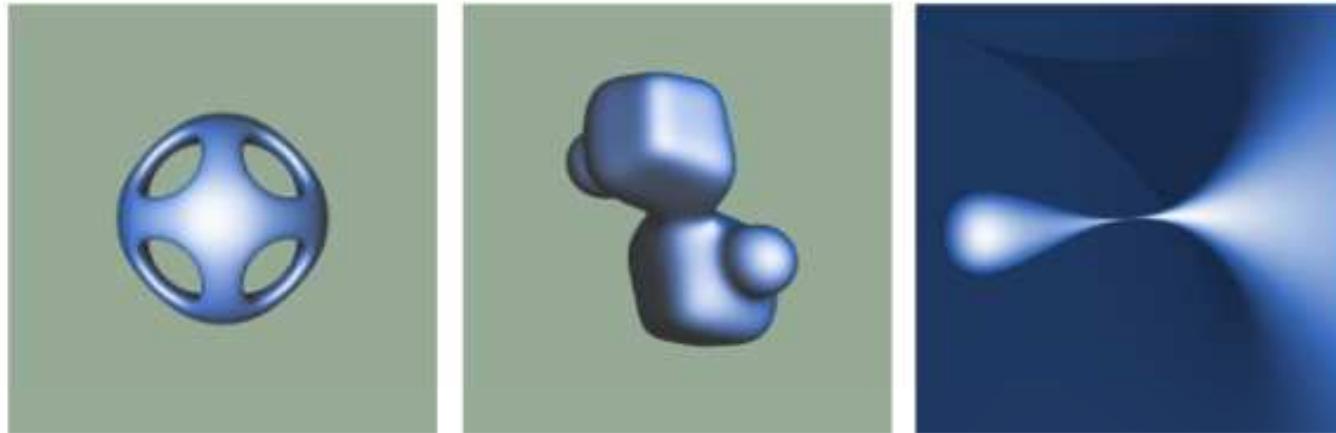
Inclusion Function :

$$F(T') = F(l_x + T'(X'_p - l_x), l_y + T'(Y'_p - l_y), l_z + T'(Z'_p - l_z)) , \quad T' = [0, \infty]$$



## Improving Efficiency

### Some results



Strategy: Four rays in undefined areas, one ray in other areas

Surface	Presented Method		Previous technique		% Improvement
	Time	Rays Traced	Time	Rays Traced	
Orthocircle	8,8	68631	21,1	375003	139%
Blob	11,6	58273	35,6	414406	205%
Drop	35	460495	106	1620000	202%



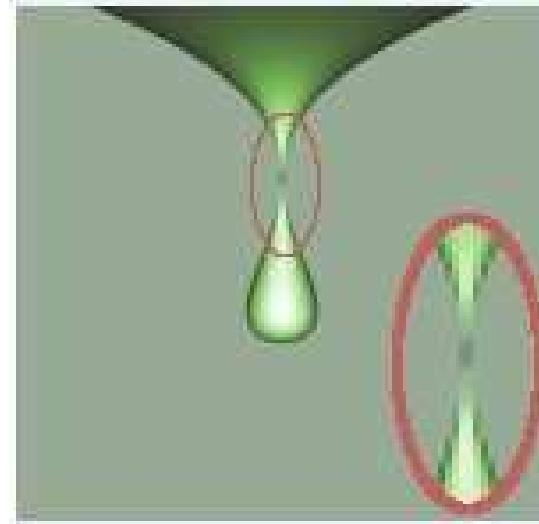
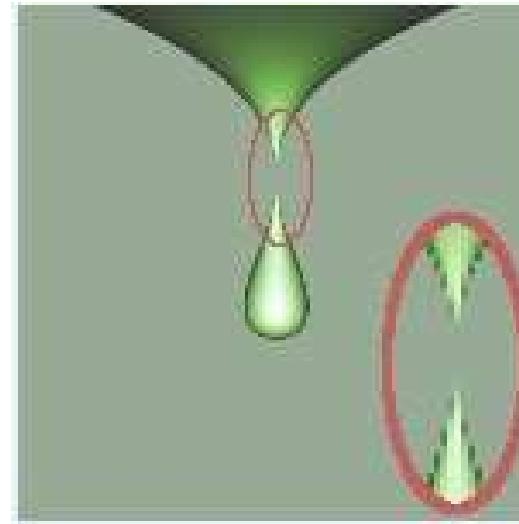


## Section 3

# Anti aliasing Algorithm



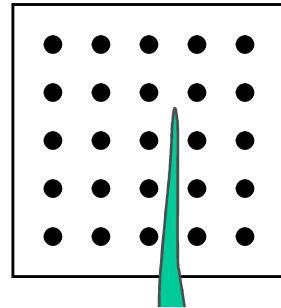
### Aliasing in Ray Tracing of IS



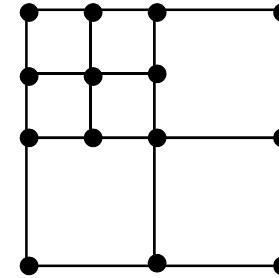
- Aliasing problems appear even when IA is applied in the intersection test.



### Anti aliasing Techniques



Regular Sampling



Adaptive Sampling

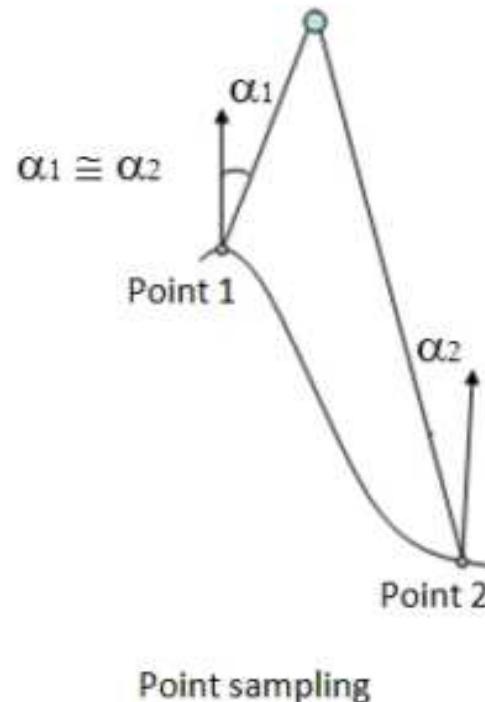
- There are many anti aliasing techniques: adaptive sampling, cone tracing, beam tracing
- Adaptive sampling is still “sampling”
  - Bounding boxes for small objects
  - Problems with long thin objects (J. Genetti et al)
- Neighbor information (beam tracing, cone tracing)
  - Complex intersection test (J. Amanatides)



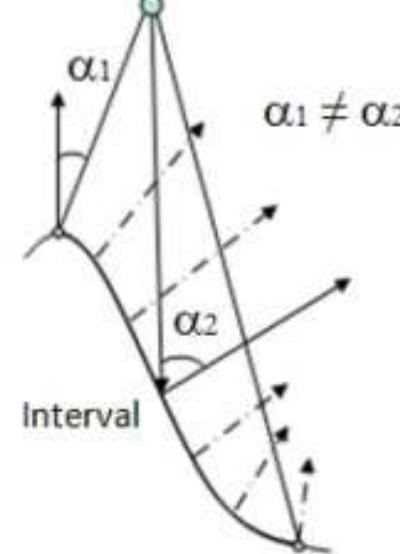


### Interval Adaptive Anti aliasing (IAA)

- Use a beam representing a set of rays
- IAA allows to know variation over all the rays intersecting a surface inside an area, not only between points.



Point sampling



IAA algorithm



### Results of IAA

Only IA



Using IAA





**Thank you!**

**Questions?**