

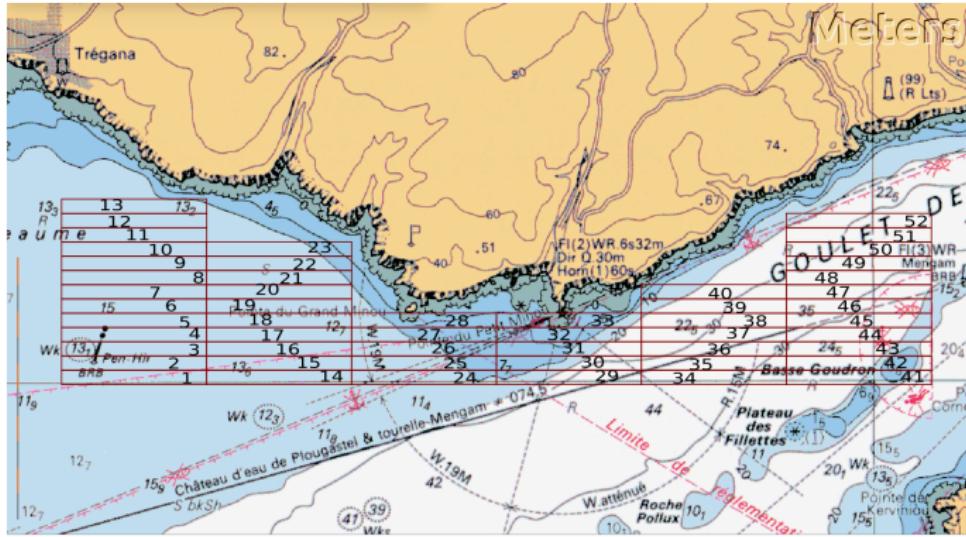
# Ocean exploration with underwater robots

L. Jaulin

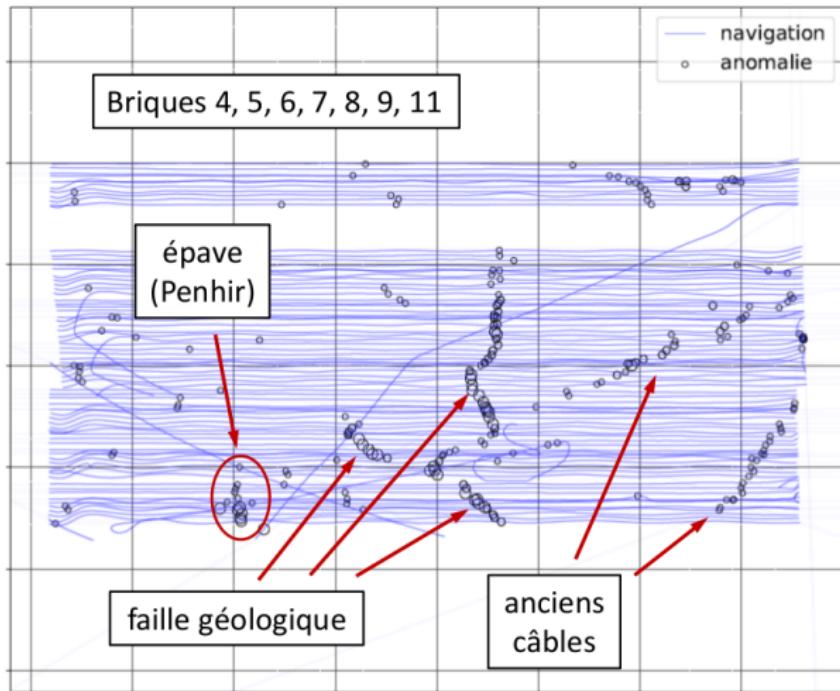
October 21, 2020,  
Exposé au CD du GDR MACS



# 1. Marine robots to build maps





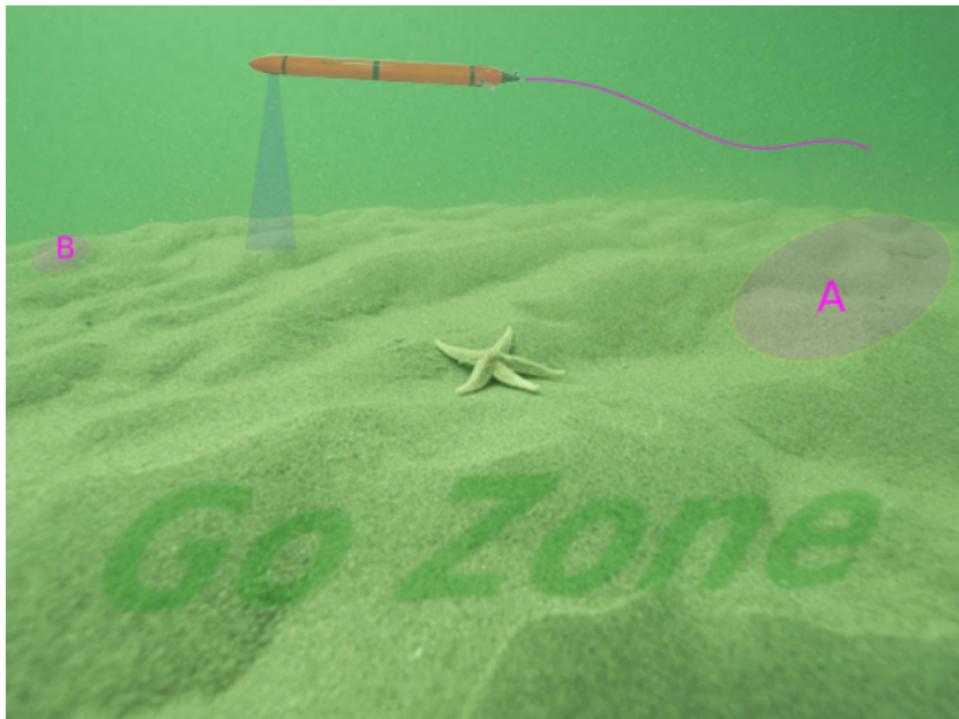


Magnetic map built in 2018

## 2. Cycle-based navigation

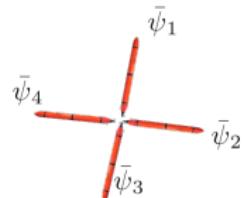
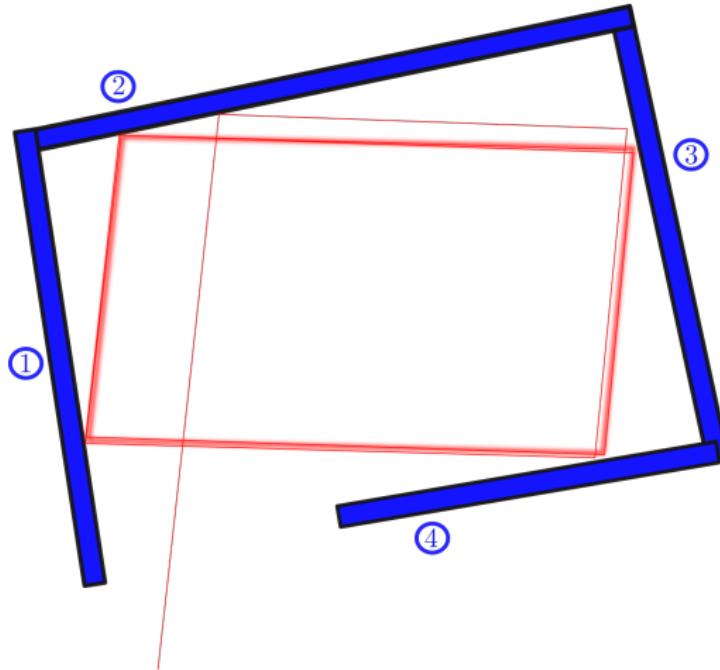


Submeeting 2018





[youtu.be/TsvEUGa-XAs](https://youtu.be/TsvEUGa-XAs)





Find the route without GPS, compass and clock

### 3. Tools for validation

Given

$$\begin{cases} \dot{\mathbf{x}} = \mathbf{f}(\mathbf{x}) \\ \mathbf{x}_0 \in [\mathbf{x}_0] \end{cases}$$

Interval methods allow us to find an envelope for  $\mathbf{x}(t)$ .