



Attraction domain of a nonlinear system using interval analysis.

Nicolas Delanoue¹, Luc Jaulin², Bertrand Cottenceau¹

¹ Laboratoire d'Ingénierie des Systèmes Automatisés
LISA FRE 2656 CNRS, Université d'Angers
62, avenue Notre Dame du Lac - 49000 Angers
{nicolas.delanoue, bertrand.cottenceau}@istia.univ-angers.fr

² Laboratoire E^3I^2
ENSIETA, 2 rue François Verny
29806 Brest Cedex 09
luc.jaulin@ensieta.fr

Abstract. Consider a given dynamical system, described by $\dot{x} = f(x)$ (where f is a nonlinear function) and $[x_0]$ a subset of \mathbb{R}^n . We present an algorithm, based on interval analysis, able to show that there exists a unique equilibrium state $x_\infty \in [x_0]$ which is asymptotically stable. The effective method also provides a set $[x]$ (subset of $[x_0]$) which is included in the attraction domain of x_∞ .

In a second time, the flow of the equation $\dot{x} = f(x)$ is discretized and inclusion methods are combined with graph theory to compute a set which is included in the attraction domain.

keywords :

interval computations, reliable algorithm, stability of nonlinear system, attraction domain.

1 Introduction

There is a considerable number of works devoted to the stability problem of dynamical systems $\dot{x} = f(x)$ using interval computations [13] [14] [15] [16]. We recall some definitions and notations related to stability.

Consider a dynamical system

$$\dot{x} = f(x) \tag{1}$$

where $f : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a differentiable function. Let $\{\varphi^t\}$ denotes the flow associated to the vector field $x \mapsto f(x)$.

Definition 1. A subset D of \mathbb{R}^n is stable if $\varphi^{\mathbb{R}^+}(D) \subset D$, where $\varphi^{\mathbb{R}^+}(D) = \{\varphi^t(x), x \in D, t \in \mathbb{R}^+\}$

Definition 2. Let D and D' be two subsets of \mathbb{R}^n such that $D \subset D'$. A equilibrium point x_∞ is asymptotically (D, D') -stable if $\varphi^{\mathbb{R}^+}(D) \subset D'$ and $\varphi^\infty(D) = \{x_\infty\}$, where $\varphi^\infty(D)$ denotes the set $\{x_\infty \in \mathbb{R}^n \mid x_\infty = \lim_{t \rightarrow \infty} \varphi^t(x), x \in D\}$

When f is sufficiently regular around an equilibrium state x_∞ and $Df(x_\infty)$ is hyperbolic, the qualitative behavior of the dynamical system $\dot{x} = f(x)$ around x_∞ is the same that of $\dot{x} = Df(x_\infty)(x - x_\infty)$, the stability of which can be determined by counting the number of eigenvalues with negative real parts. Now, in practice, we are only able to compute an approximation \tilde{x}_∞ of x_∞ and thus we cannot conclude to the local stability of (1) around x_∞ .

Moreover, even if we were able to compute exactly x_∞ and to prove its local stability, to our knowledge, no general method seems to be available to compute a neighborhood D of x_∞ such that $\varphi^\infty(D) = \{x_\infty\}$.

The main contribution of this paper is a method to compute :

- from a set D' , a domain D such that the system is (D, D') -stable.
- a domain $A \supset D$ such that A is included in the attraction domain of $\{x_\infty\}$.

The approach to be considered is based on interval analysis. Interval analysis is used to prove uniqueness of an equilibrium state. The paper provides a method and a sufficient condition to check that a real valued function is positive. An algorithm combines interval analysis and Lyapunov to solve our stability problem is proposed.

May, 2006

2 Asymptotic stability

Consider the example :

$$\begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \end{pmatrix} = \begin{pmatrix} -x_2 \\ x_1 - (1 - x_1^2)x_2 \end{pmatrix} \quad (2)$$

where $[x_0] = [-0.6, 0.6]^2$.

The vector field associated to this dynamical system is represented on Figure 1. To prove existence and uniqueness of the equilibrium state $x_\infty \in [x]_\infty$, one uses the famous interval Newton method.

To compute a set $[x]$ included in the attraction domain of x_∞ , one combines interval analysis and Lyapunov theory. In this case, the Lyapunov function created is :

$$L_{x_\infty}(x) = (x - x_\infty)^T \begin{pmatrix} -1,51 & 0,49 \\ 0,49 & -1,01 \end{pmatrix} (x - x_\infty) \quad (3)$$

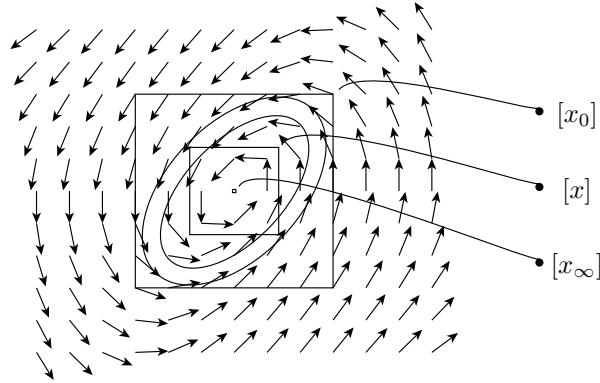


Fig. 1. Lyapunov function level curves and a box $[x_\infty]$ which contains a unique equilibrium state.

3 Attraction domain

The previously computed set $[x]$ is in the attraction domain of x_∞ . The proposed method improves $[x]$ combining inclusion methods and graph theory. (Initialization $A \leftarrow [x]$). Given an ordinary differential equation, inclusion methods gives inclusion function of the flow. From $t \in \mathbb{R}$ and a cover $\{\mathbb{S}_i\}$ of D , the proposed method creates a relation (a graph) \mathcal{R} with :

$$\mathbb{S}_i \mathcal{R} \mathbb{S}_j \Leftrightarrow \varphi^t(\mathbb{S}_i) \cap \mathbb{S}_j \neq \emptyset$$

If $\mathbb{S}_i \mathcal{R} \mathbb{S}_j \Rightarrow \mathbb{S}_j \subset A$ then \mathbb{S}_i is added to A ($A \leftarrow A \cup \mathbb{S}_i$). This algorithm converges to a set which is included in the attraction domain of x_∞ .

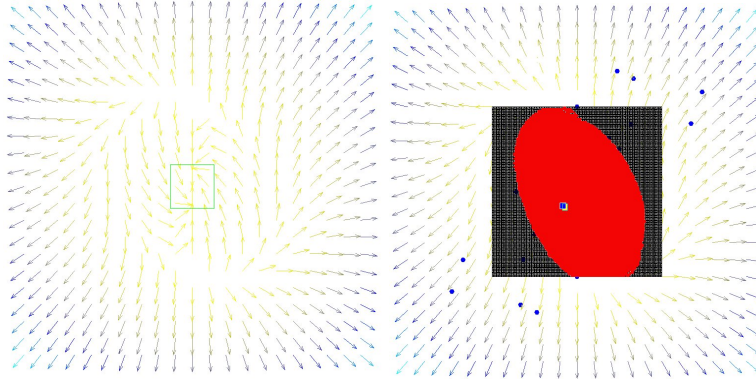


Fig. 2. The computed set A is included in the attraction domain of the equilibrium state.

References

1. R. E. Moore, *Interval Analysis*, Prentice-Hall, Englewood Cliffs, NJ, 1996
2. R. E. Moore, *Practical aspects of interval computation*, Appl. Math., 13, pages 52-92
3. A. Neumaier *Interval Methods for Systems of Equations* Encyclopedia of Mathematics and its Applications 37, Cambridge Univ. Press, Cambridge 1990 255 pp.
4. G. Alefeld, *Inclusion methods for systems of nonlinear equations - the interval Newton method and modifications.*, In "Topics in Validated Computation". Proceedings of the IMACS-GAMM International Workshop on Validated Computation, Oldenburg, Germany, August 30 - September 3, 7-26, 1993. (Editor: J. Herzberger. Elsevier Amsterdam 1994).
5. J.H. Davenport, Y.Siret, E.Tournier, *Computer Algebra, Systems and Algorithms for Algebraic Computation*, Academic Pr; 2nd edition (June 1993), ISBN: 0-12204-232-8.
SIAM Journal on Matrix Analysis and Applications, Volume 15, Number 1, pp. 175-184, 1994 Society for Industrial and Applied Mathematics,
6. Jiri Rohn, *Positive Definiteness and Stability of Interval Matrices*, SIAM Journal on Matrix Analysis and Applications, Volume 15, Number 1, pp. 175-184, 1994 Society for Industrial and Applied Mathematics,
7. M. Berz, K.Makino, *Verified Integration of ODEs and flows Using Differential Algebraic methods on High-Order Taylor Models*. Reliable Computing, 4(4) : 361-369, 1998.
8. T. Rassi, N. Ramdani and Y. Candau. *Set membership state and parameter estimation for systems described by nonlinear differential equation*. Automatica, 40 : 1771-1777,2004.
9. Slotine, J.J.E., and Li, W., *Applied Nonlinear Control*, Prentice-Hall, 1991.
10. Jaulin L., M. Kieffer, O. Didrit and E. Walter *Applied Interval Analysis with Examples in Parameter and State Estimation, Robust Control and Robotics*, Springer-Verlag, ISBN: 1-85233-219-0, (2001).
11. Revol N. *Interval Newton iteration in multiple precision for the univariate case Numerical Algorithms*, vol 34, no 2, pp 417-426, 2003
12. L. Jaulin, and D. Henrion, *Contracting optimally an interval matrix without losing any positive semi-definite matrix is a tractable problem*, Reliable Computing, Volume 11, issue 1, pages 1-17. (2005)
13. Kharitonov V.L., *About an asymptotic stability of the equilibrium position of linear differential equations systems family* Differential equations. 1978. 14. N 11. pp.2086-2088 (in Russian).
14. Bialas S., *A necessary and sufficient condition for stability of interval matrices* Int. J. Contr. 1983.
15. Karl W.C., Greschak J.P., Verghese G.C., *Comments on a necessary and sufficient condition for stability of interval matrices* Int. J. Contr. 1984.
16. Kreinovich V., Lakeyev A., Rohn J., Kahl P., *Computational complexity and feasibility of data processing and interval computations*. Kluwer, Dordrecht, 1997.