

Identification of fuzzy regression models

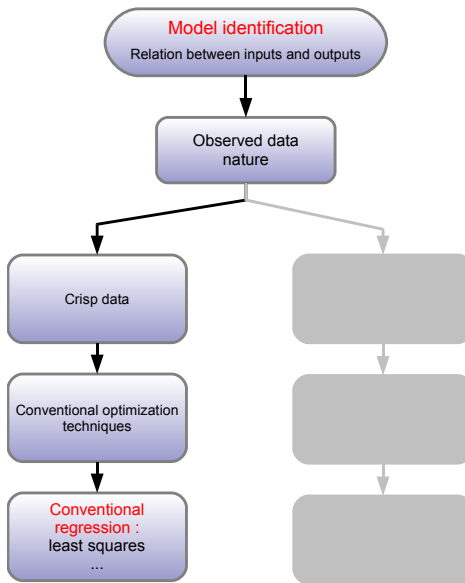
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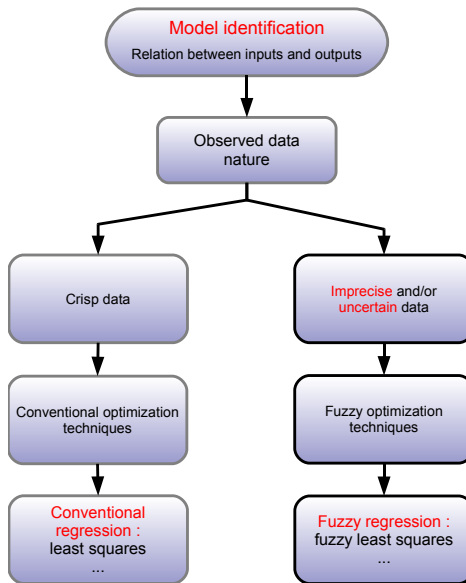
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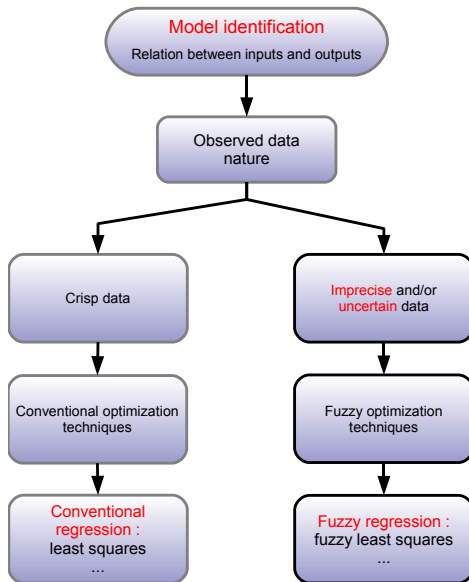
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- ② Notations and concepts
- ③ Fuzzy linear regression
- ④ Proposed approach
- ⑤ Illustrative examples
- ⑥ Conclusion

Introduction



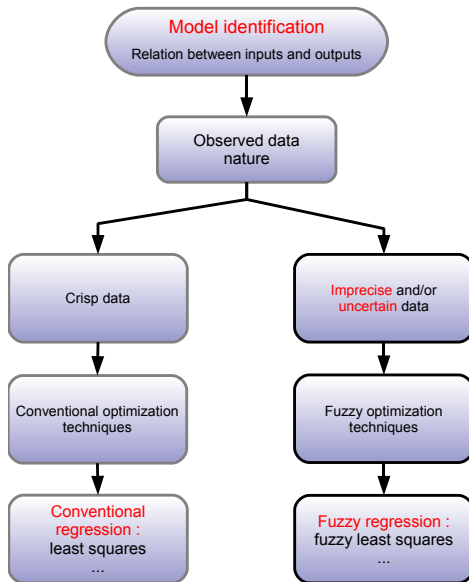
Introduction





General problem

- What kind of fuzzy models have to be used ?
- What kind of data have to be manipulated for the identification process ?



General problem

- What kind of fuzzy models have to be used ?
- What kind of data have to be manipulated for the identification process ?

⇒ How can we identify a fuzzy model on this kind of data ?

Notations and concepts



Considered model : multi-inputs, single-ouput

- Objective : to determine a relationship $Y = h(\mathbf{x})$ between inputs and output
- h considered as linear \rightarrow model of the form :

$$Y = \sum_{i=1}^N A_i \cdot x_i$$

- fuzzy model : fuzzy coefficients A_i

Observed data for the identification

Set of M observed data :

The j^{th} data :

- a crisp inputs vector $x_j = (x_{0j}, x_{1j}, \dots, x_{Nj})$
- the corresponding fuzzy output Y_j
 - a symmetrical triangular fuzzy number

Remark : choice made for the sake of simplicity

Conventional intervals

- Set of elements in \mathbb{R} between a lower and an upper bound

$$a = \{x | a^- \leq x \leq a^+, x \in \mathbb{R}\}$$

- Midpoint and Radius

$$M(a) = M_a = (a^- + a^+)/2$$

$$R(a) = R_a = (a^+ - a^-)/2$$

- calculus on sets

Conventional intervals

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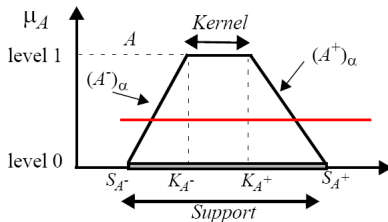
Conventional intervals : inclusion

- general relationship :

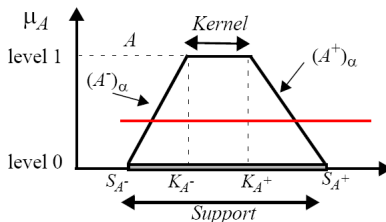
$$a \subseteq b \Leftrightarrow |M(b) - M(a)| \leq R(b) - R(a)$$

Fuzzy intervals

- Horizontal AND vertical dimension
- ⇒ intervals at two levels :
- kernel : $K_A = [K_A^-, K_A^+]$
 - support : $S_A = [S_A^-, S_A^+]$
- **Kernel included in the Support**
 - function linking the two levels : profiles
 - α -cut ⇒ conventional interval



Notations and concepts



Fuzzy intervals : linear profiles

- general case : trapezoidal fuzzy interval

$$A = (K_A, S_A) = ([K_A^-, K_A^+], [S_A^-, S_A^+])$$

- a particular case : symmetrical triangular fuzzy interval

$$A = (K_A, R_A)$$

Notations and concepts

- inclusion of two fuzzy intervals : general definition

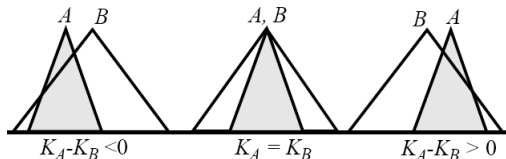
$$A \subseteq B \Leftrightarrow \forall x, \mu_A(x) \leq \mu_B(x)$$

- in the case of trapezoidal fuzzy intervals :

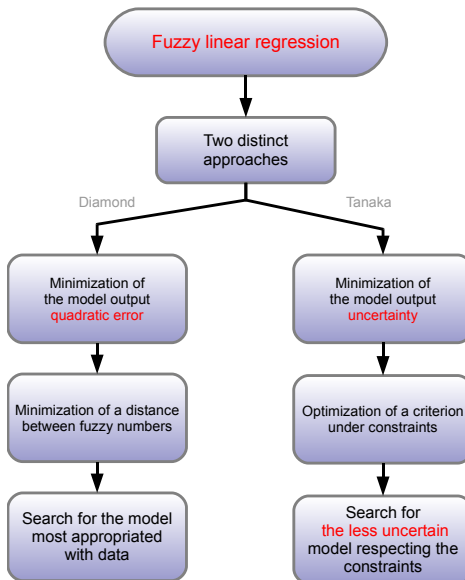
$$A \subseteq B \Leftrightarrow K_A \subseteq K_B \text{ et } S_A \subseteq S_B$$

- in the case of symmetrical triangular fuzzy intervals :

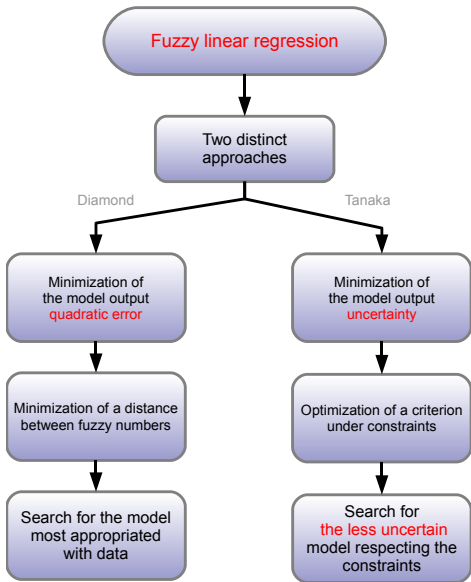
\Rightarrow equality of the Kernel values



Fuzzy linear regression



Fuzzy linear regression

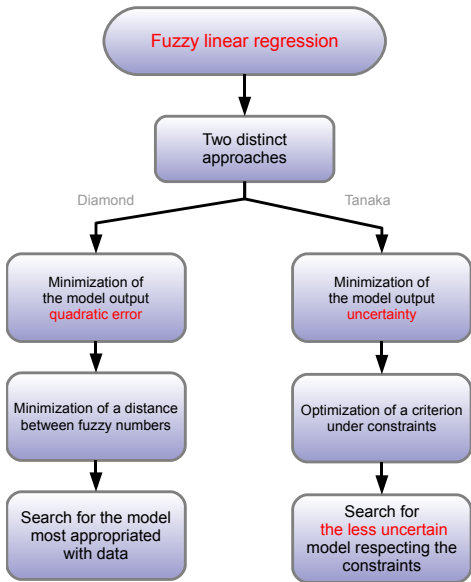


Which constraints ?

Relationship between observed and predicted outputs :

- *necessity* model : predicted outputs included in observed ones
- *conjunction* model : no empty intersection between predicted and observed outputs

Fuzzy linear regression



Which constraints ?

Relationship between observed and predicted outputs :

- *necessity* model : predicted outputs included in observed ones
- *conjunction* model : no empty intersection between predicted and observed outputs
- *possibility* model : observed outputs included in predicted ones

⇒ data total uncertainty is taken in care

Context of the study

- observed outputs : symmetrical triangular fuzzy intervals
⇒ identified model with triangular parameters
- study leaded for the identification of single input models :

$$\hat{Y}(x) = A_0 \oplus A_1 x$$

with \oplus sum of fuzzy intervals

✓ *concepts can be extended to the multi inputs case*

- **possibility model** : observed inputs included in predicted ones

Basic concepts

- use of α -cuts
 - ⇒ conventionnal intervals are handled
- minimization of a linear criterion under constraints :
 - ⇒ criterion : a representation of the model uncertainty
 - ⇒ constraints : inclusion of conventional intervals at the level α

↔ What are the limits of this approach ?

The use of α -cuts

- inclusion constraints defined for this level α :

$$[Y_j]_\alpha \subseteq [\hat{Y}_j]_\alpha$$

$$\Leftrightarrow \begin{cases} K_{\hat{Y}_j} + (1 - \alpha)R_{\hat{Y}_j} \geq K_{Y_j} + (1 - \alpha)R_{Y_j} \\ K_{\hat{Y}_j} - (1 - \alpha)R_{\hat{Y}_j} \leq K_{Y_j} - (1 - \alpha)R_{Y_j} \end{cases}$$

- after the identification : parameters considered as valid $\forall \alpha \in [0, 1]$
- BUT : triangular identified model, *equality of the Kernels necessary* for the total inclusion
- **Total inclusion $\forall \alpha \in [0, 1]$ not guaranteed !**

Conventionnal criteria

- Minimization of the model uncertainty

⇒ How can it be quantified ?

↪ Most used criterion (Tanaka) : **sum of the predicted intervals radius**

$$Somme = M \cdot R_{A_0} + R_{A_1} \cdot \sum_{j=1}^M |x_j|$$

- BUT : minimization at the observed points

⇒ strongly dependant on the learning points : **weak robustness**

Model representativity

Conventionnal linear model : study of the output variation on the domain

- kernel : $M(\hat{Y}(x)) = K_{\hat{Y}(x)} = K_{A_0} + K_{A_1} \cdot x$

⇒ variation according to the sign of $K_{A_1} \rightarrow$ **any variation**

- radius : $R(\hat{Y}(x)) = R_{\hat{Y}(x)} = R_{A_0} + R_{A_1} \cdot |x|$

⇒ **Radius always positive !**

⇒ **Variation of the output radius limited by the input sign**

Points to improve in the previous method : summary

- Is it possible to consider a **model respecting the inclusion $\forall \alpha \in [0, 1]$** ?
- Is it possible to identify such a model with a **more robust criterion** ?
- Is it possible to **improve the representativity** of a fuzzy linear model ?

Solution to the inclusion problem

- **identification of a trapezoidal fuzzy model**

→ inclusion constraints at two levels α : $\alpha = 0$ and $\alpha = 1$

- $\alpha = 1$: $K_{Y_j} \in [K_{\hat{Y}_j}^-, K_{\hat{Y}_j}^+]$
- $\alpha = 0$: $[K_{Y_j} - R_{Y_j}, K_{Y_j} + R_{Y_j}] \subseteq [S_{\hat{Y}_j}^-, S_{\hat{Y}_j}^+]$

→ linear membership function

⇒ **inclusion guaranteed $\forall \alpha \in [0, 1]$**

Remark : model output for a data j :

$$\hat{Y}_j = ([K_{\hat{Y}_j}^-, K_{\hat{Y}_j}^+], [S_{\hat{Y}_j}^-, S_{\hat{Y}_j}^+])$$

A more robust criterion

- **Objective** : make the criterion independant of data

- definition of a total uncertainty on the domain D
- vertical dimension (trapezes) taken into account
- ⇒ Minimization of **Volume** delimited by the model on D

$$Volume = R(K_{A_0}) + R(S_{A_0}) + (R(K_{A_1}) + R(S_{A_1})) \cdot |M(D)|$$

- ↪ independant of observed inputs x_j
- ↪ still linear criterion

A model more representative of the data

- To have any kind of the output radius variation :
 - the input variable sign must be modified
 - the linear behavior must be kept

⇒ The origin of the model is set on a bound of $D = [x_{min}, x_{max}]$

⇒ New model defined on the domain D :

$$\hat{Y}(x) = A_0 \oplus A_1(x - \text{shift})$$

Study of the variation of this new model output radius

$$R([S_{\hat{Y}}]) = R([S_{A_0}]) + R([S_{A_1}]) \cdot |x - \text{shift}|$$

- $x - \text{shift} \geq 0 \ \forall x \in D \Rightarrow$ increasing radius
- $x - \text{shift} \leq 0 \ \forall x \in D \Rightarrow$ decreasing radius

output spread variation	↗	↘
Used model	$A_0 \oplus A_1(x - x_{min})$	$A_0 \oplus A_1(x - x_{max})$

Identification method : summary

Main steps

- What is the global tendency of the observed outputs radius on D ?
⇒ Choice of the appropriated value of shift
- Identification of trapezoidal coefficients :
⇒ Minimization of the criterion **Volume** under the inclusion constraints :
 - at $\alpha = 0$ and $\alpha = 1 \rightarrow$ total inclusion guaranteed

Optimization linear program

$$\text{Min } R(K_{A_0}) + R(S_{A_0}) + (R(K_{A_1}) + R(S_{A_1})) \cdot |M(D)|$$

$$\text{s.c. } \begin{cases} K_{Y_j} \in [K_{\hat{Y}_j}^-, K_{\hat{Y}_j}^+] \\ [K_{Y_j} - R_{Y_j}, K_{Y_j} + R_{Y_j}] \subseteq [S_{\hat{Y}_j}^-, S_{\hat{Y}_j}^+] \end{cases}$$

Performance indicators

Comparison of two models : it is necessary to use **performance indicators**

Two approaches :

- indicators about the model uncertainty :
 - **Sum** of the radius
 - **Volume** delimited by the model on D
- indicators about the model fitting with data
 - **Compatibility** between observed and predicted data : inclusion degree
 - **Distance** between observed and predicted data : quadratic error

Extension to piecewise linear models

Global model :

- shifted submodels with trapezoidal coefficients
 - each submodel defined on its own domain
- ⇒ independant submodels for identification and using

Identification method :

- data segmentation :
 - on observed kernels
 - on observed radius

⇒ More representative models !
 - optimization of the parameters with the criterion **Volume**
- ⇒ identification of a gobal model with a minimal uncertainty and respecting the total inclusion

Generalization to multi-inputs models

Previous concepts applicable to multi-inputs ($x_i, i = 1, \dots, N$)

- Trapezoidal coefficients
- Appropriated shift for each x_i
- Criterion **Volume** can be extended, still linear

⇒ identification of the optimal model for the total output uncertainty on the domain

Case of a piecewise model

- Data segmentation : cartesian product
- Identification of submodels

⇒ Independant submodels on each region

Numerical examples : inclusion problem

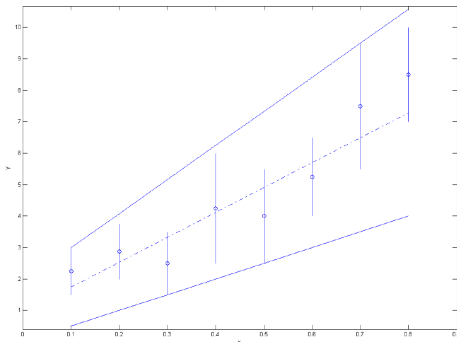
j	x_j	Y_j
1	0.1	(2.25, 0.75)
2	0.2	(2.875, 0.875)
3	0.3	(2.5, 1)
4	0.4	(4.25, 1.75)
5	0.5	(4.0, 1.5)
6	0.6	(5.25, 1.25)
7	0.7	(7.5, 2)
8	0.8	(8.5, 1.5)

- 8 observed data, $D = [0.1, 0.8]$
- crisp inputs
- observed outputs : symmetrical triangular fuzzy numbers
- form of the identified model :

$$\hat{Y}(x) = A_0 \oplus A_1 x$$

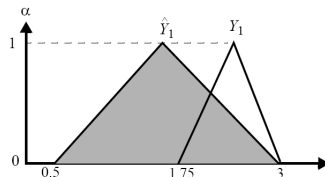
Numerical examples : inclusion problem

Triangular coefficients : identification at $\alpha = 0$



	<i>modèle flou triangulaire</i>
A_0	(0.96, 0.96)
A_1	(7.92, 2.92)
Compatibilité	0.83

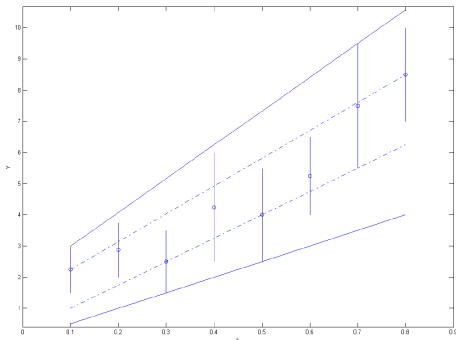
study of the inclusion : data $j = 1$



- inclusion is respected at $\alpha = 0$
- inclusion is not guaranteed $\forall \alpha$

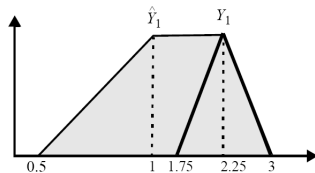
Numerical examples : inclusion problem

Trapezoidal coefficients



	modèle flou trapézoïdal
A_0	$([0.25 \ 1.36], [0 \ 1.92])$
A_1	$([7.5 \ 8.93], [5 \ 10.83])$
compatibilité	1

study of the inclusion : data $j = 1$



• inclusion is respected $\forall \alpha$!

Numerical examples : criterion robustness

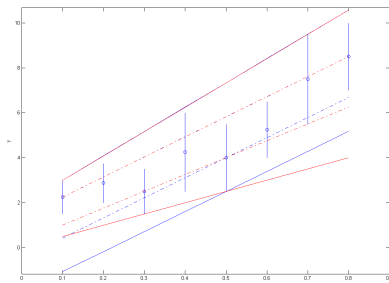
presentation of the data set

- data $j = 8$ duplicated three times, $D = [0.1, 0.8]$
- ⇒ study of the influence of **data redundancy**
- trapezoidal identified model
- 2 minimized criteria : *Sum* and *Volume*

	<i>Somme</i>	<i>Volume</i>
A_0	$([-0.46 \ 1.36], [-1.96 \ 1.92])$	$([0.25 \ 1.36], [0 \ 1.92])$
A_1	$([8.93 \ 8.93], [8.93 \ 10.83])$	$([7.5 \ 8.93], [5 \ 10.83])$
<i>distance</i>	71.05	91.29
<i>somme</i>	37.08	38.42
<i>volume</i>	3.28	3.15

- initial model identified again for *Volume*
- **Minimal total uncertainty**
- the indicators *distance* and *sum* are not robust !

Identified models : *Sum* (blue) and *Volume* (red)



Numerical examples : output representativity

presentation of the data set

- initial data shifted to have negative inputs
- ⇒ increasing outputs radius
- trapezoidal identified models, for the minimum *Volume* :
 - conventionnal model : $\hat{Y}(x) = A_0 \oplus A_1 x$
 - shifted model : $\hat{Y}(x) = A_0 \oplus A_1(x - \text{shift})$

j	x_j	Y_j
1	-0.8	(2.25, 0.75)
2	-0.7	(2.875, 0.875)
3	-0.6	(2.5, 1)
4	-0.5	(4.25, 1.75)
5	-0.4	(4.0, 1.5)
6	-0.3	(5.25, 1.25)
7	-0.2	(7.5, 2)
8	-0.1	(8.5, 1.5)

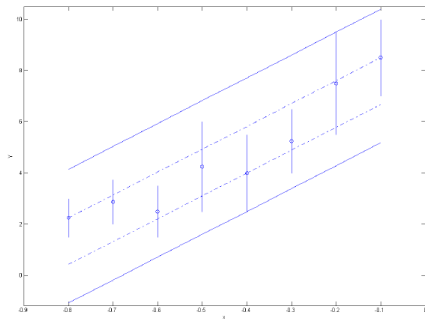
	$\hat{Y}(x) = A_0 \oplus A_1 \cdot x$	$\hat{Y}(x) = A_0 \oplus A_1(x - \text{shift})$
A_0	[[7.57 9.39],[0.07 11.29]]	[[1 2.25],[0.5 3]]
A_1	8.93	[[7.5 8.93],[5 10.83]]
<i>distance</i>	58.83	48.08
<i>somme</i>	28.14	25.17
<i>volume</i>	3.52	3.15

All the indicators are better for the shifted model !

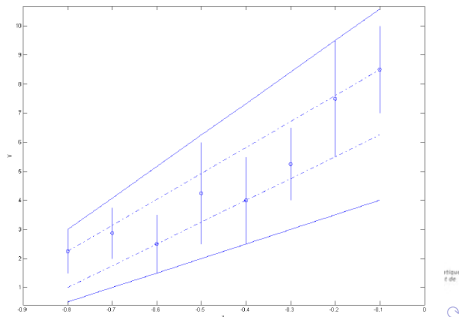
Numerical examples : output representativity

	$\hat{Y}(x) = A_0 \oplus A_1 \cdot x$	$\hat{Y}(x) = A_0 \oplus A_1(x - shift)$
A_0	([7.57 9.39],[0.07 11.29])	([1 2.25],[0.5 3])
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<i>distance</i>	58.83	48.08
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Conventionnal model

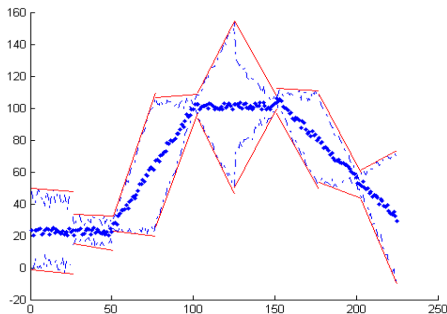


Model with shifted input



Numerical examples : piecewise model

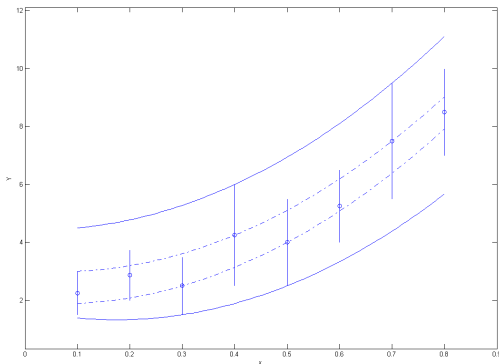
- Great number of data
 - Various tendencies of kernel and radius variations, noise : segmentation
- ⇒ Identification of shifted trapezoidal multi-inputs submodels
- ⇒ Identification of the optimal global model for the **minimal uncertainty (Volume)**



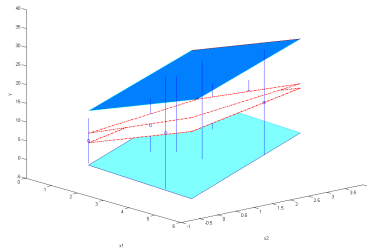
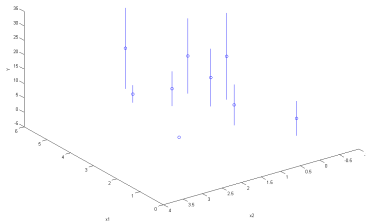
Numerical examples : higher order model

- Initial data set
- 2-order identified model :

$$\hat{Y}(x) = A_0 \oplus A_1x \oplus A_2x^2$$



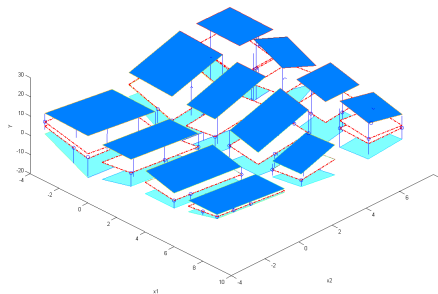
Numerical examples : multi-inputs model



- Two inputs \rightarrow two appropriated values of shifts :
 - Increasing radius on x_1 and decreasing one on x_2
 - Identification of the trapezoidal model for **Volume**
- \Rightarrow "Planes" with total inclusion of data

Numerical examples : multi-inputs piecewise model

- Various tendencies of kernel and radius variations : segmentation
 - ⇒ Identification of shifted trapezoidal multi-inputs submodels
 - ⇒ Identification of the optimal global model for the **minimal uncertainty (Volume)**



Propositions

- Identification of trapezoidal models : **total inclusion is guaranteed**
- Improvement of the **model representativity**
- Identification for the minimal total uncertainty : **increased robustness**
- Application of these concepts on **piecewise linear regression** problems

Future work

- Imprecise observed inputs
 - Uncertainty comes from :
 - fuzzy parameters
 - fuzzy inputs
 - Lack of representativity of conventionnal space (X, Y)
- ⇒ Representation of the model in the space $(Mid(X), Rad(X), Y)$
- ⇒ Identification of the model in this space

END
Questions ?...