Polyhedral Relaxations for Constraint Satisfaction Problems

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Problem formulation

Notation

An interval matrix

$$\mathbf{A} := [\underline{A}, \overline{A}] = \{ A \in \mathbb{R}^{m \times n} \mid \underline{A} \le A \le \overline{A} \}.$$

The midpoint and radius matrices

$$A_c := rac{1}{2}(\overline{A} + \underline{A}), \quad A_\Delta := rac{1}{2}(\overline{A} - \underline{A}).$$

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Constraint programming problem

Enclose the set $\mathcal S$ described by

$$\begin{aligned} f_i(x_1, \dots, x_n) &= 0, \quad i = 1, \dots, m, \\ g_j(x_1, \dots, x_n) &\leq 0, \quad j = 1, \dots, \ell, \end{aligned} (\begin{array}{c} f(x) &= 0 \\ (g(x) &\leq 0 \end{array}) \end{aligned}$$

on a box x.

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Our approach

- linearize constraints,
- compute new bounds and iterate.

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Interval linearization

Let $x^0 \in \mathbf{x}$, called the center. Suppose that a function $h : \mathbb{R}^n \mapsto \mathbb{R}^s$ satisfies

$$h(x) \subseteq S_h(\mathbf{x}, x^0)(x - x^0) + h(x^0), \quad \forall x \in \mathbf{x}$$

for a suitable interval-valued function $S_h : \mathbb{IR}^n \times \mathbb{R}^n \mapsto \mathbb{IR}^{s \times n}$.

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Techniques

- mean value form
- slopes
- special structure analysis (McCorming-like linearizations ...)

Interval linear programming formulation

Now, the set ${\mathcal S}$ is enclosed by a set described by

$$A(x - x^0) + f(x^0) = 0$$
, for some $A \in \mathbf{A}$,
 $B(x - x^0) + g(x^0) \le 0$, for some $B \in \mathbf{B}$,

for some interval matrices **A** and **B**.

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What remains to do

• Solve the interval linear program

• choose $x^0 \in \mathbf{x}$

Vertex selection of x^0

Case $x^0 := \underline{x}$

Let $x^0 := \underline{x}$. Since $x - \underline{x}$ is non-negative, the solution set to

$$A(x-x^0)+f(x^0)=0, \quad ext{for some } A\in \mathbf{A}, \ B(x-x^0)+g(x^0)\leq 0, \quad ext{for some } B\in \mathbf{B},$$

is described by

$$\underline{A}x \leq \underline{A}\underline{x} - f(\underline{x}), \quad \overline{A}x \geq \overline{A}\underline{x} - f(\underline{x}),$$

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• Araya, Trombettoni & Neveu (2012) recommend two opposite corners

General case

Let $x^0 \in \mathbf{x}$. The solution set to

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$$egin{aligned} |A_c(x-x^0)+f(x^0)| &\leq A_\Delta |x-x^0|, \ B_c(x-x^0) &\leq B_\Delta |x-x^0|-g(x^0). \end{aligned}$$

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- Non-linear description due to the absolute values.
- How to get rid of them?

Solution

Linearize the absolute values.

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Theorem (Beaumont, 1998)

For every $y \in \mathbf{y} \subset \mathbb{R}$ with $\underline{y} < \overline{y}$ one has

$$|\mathbf{y}| \le \alpha \mathbf{y} + \beta, \tag{(*)}$$

where

$$\alpha = \frac{|\overline{y}| - |\underline{y}|}{\overline{y} - \underline{y}} \text{ and } \beta = \frac{\overline{y}|\underline{y}| - \underline{y}|\overline{y}|}{\overline{y} - \underline{y}}$$

Moreover, if $\underline{y} \ge 0$ or $\overline{y} \le 0$ then (*) holds as equation.

Let $x^0 \in \mathbf{x}$. Suppose that **A** and **B** do not depend on a selection of x^0 .

Let x⁰ ∈ x. Suppose that A and B do not depend on a selection of x⁰.
If f_i(x) are convex, then the half of the linearized inequalities is a consequence of the corresponding inequalities derived by vertices of x.

Let $x^0 \in \mathbf{x}$. Suppose that **A** and **B** do not depend on a selection of x^0 .

- If f_i(x) are convex, then the half of the linearized inequalities is a consequence of the corresponding inequalities derived by vertices of x.
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Consequences

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Consequences

- For nice functions (linear, convex), non-vertex selection of x⁰ makes no progress
- Non-vertex selection of x^0 is more useful more non-convex are f, g

Typical situation when choosing x^0 to be vertex:



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Typical situation when choosing x^0 to be the opposite vertex:



Typical situation when choosing $x^0 = x_c$:



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Typical situation when choosing $x^0 = x_c$ (after linearization):



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Image: Image:

Typical situation when choosing all of them:



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Constraints:

$$\pi^2 y - 4x^2 \sin x = 0, \quad y - \cos \left(x + \frac{\pi}{2}\right) = 0, \quad x \in \left[-\frac{\pi}{2}, \frac{\pi}{2}\right], \ y \in \left[-1, 1\right].$$

Center: $x^0 = (0, 0)$



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Contraction for centers $x^0 = (0, 0), (\frac{\pi}{2}, 0), (-\frac{\pi}{2}, 0)$



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Comparison to Parallel Linearization

Suppose that $h: \mathbb{R}^n \mapsto \mathbb{R}^s$ has the following interval linear enclosure on **x**

$$h(x) \subseteq \mathbf{A}(x - x^0) + h(x^0), \quad \forall x \in \mathbf{x}$$

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Theorem (Jaulin, 2001)

For any $A \in \mathbf{A}$ we have

$$h(x) \ge A(x-x^0) + h(x^0) + \underline{(\mathbf{A}-A)(\mathbf{x}-x^0)},$$

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Theorem

For any selection of $x^0 \in \mathbf{x}$ and $A \in \mathbf{A}$, the interval linear programming approach yields always as tight enclosures as the parallel linearization.

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Properties

• Runs in polynomial time, applicable for larger dimensions.

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 optima of underestimators (in global optimization)

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Future work

 choice of x⁰: optima of the linear programs? optima of underestimators (in global optimization) what number?



M. Hladík and J. Horáček.

Interval linear programming techniques in constraint programming and global optimization.

submitted to LNCS, 2013.